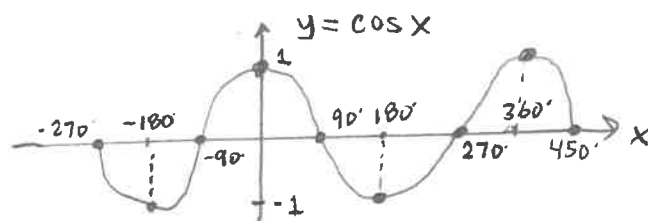
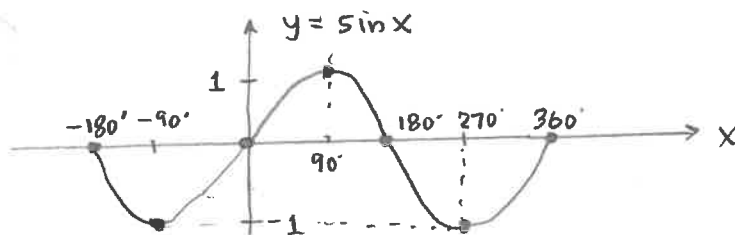


# Example 27

(Review of Some Trigonometry)

1430

Mon 3/18/21



## Some useful Trig Identities

$$\begin{aligned} \sin(-x) &= -\sin x && \text{odd function} \\ \cos(-x) &= \cos x && \text{even function} \end{aligned}$$

when sin is shifted 90° to right, you get -cos

$$\sin(x \mp 90^\circ) = \mp \cos x$$

when sin " " " " left, " " +cos

when cos is shifted 90° to right, you get +sin

$$\cos(x \mp 90^\circ) = \pm \sin x$$


" " " " " " left, " " -sin


when sin is shifted 180° left or right, you get -sin

$$\sin(x \mp 180^\circ) = -\sin x$$

when cos " " " " " " " " , you get -cos

$$\cos(x \mp 180^\circ) = -\cos x$$

Note: I do NOT memorize the above identities! 

I know the sin & cos wave forms & I understand how the above shifting affects the wave form! 

Remember!

$$\cos x \cos y = \frac{1}{2} \cos(x+y) + \frac{1}{2} \cos(x-y)$$

sum                      difference

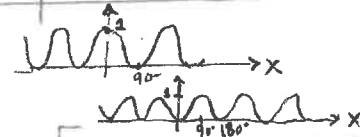
← This is TATOOED IN MY BRAIN! 

Sum-Difference cos formula

$$\Rightarrow \cos x \cos x = \frac{1}{2} \cos 2x + \frac{1}{2} \cos(0^\circ) \Rightarrow$$

$$\cos^2 x = \frac{1 + \cos 2x}{2}$$

$$\begin{aligned} \sin^2 x &= [\cos(x-90^\circ)]^2 \\ &= \frac{1}{2} \cos(2x-180^\circ) + \frac{1}{2} \cos(0^\circ) \\ &= -\frac{1}{2} \cos 2x + \frac{1}{2} \end{aligned}$$



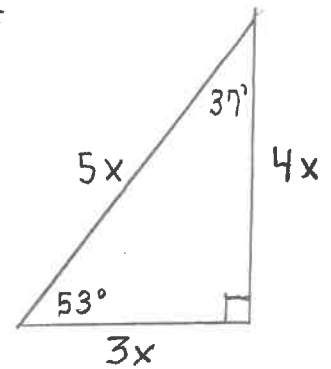
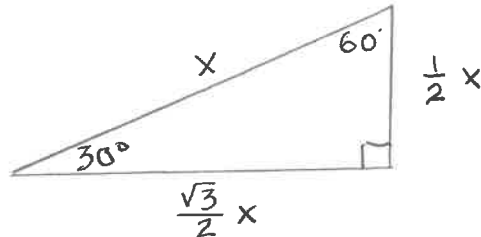
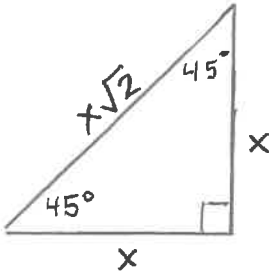
$$\sin^2 x = \frac{1 - \cos 2x}{2}$$

# Example 27

(Review of Some Trigonometry)

1440

## 3 Triangles to Remember/Memorize:



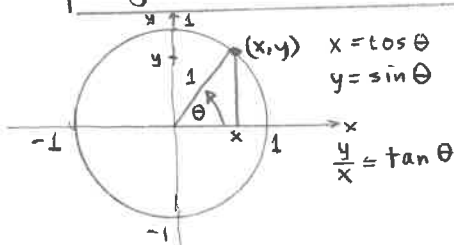
Note: There is nothing "sacred" about these triangles; i.e. it is not like they naturally arise in many real-world applications... they do not!

Why should they be remembered/memorized?

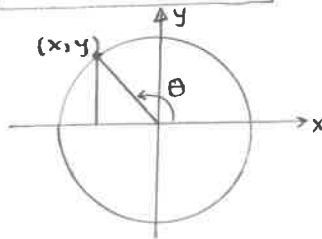
Because knowing their well-known simple trigonometry will permit you to rapidly solve problems with nicely "cooked-up" numbers so that you can more easily master the associated important fundamental concepts!



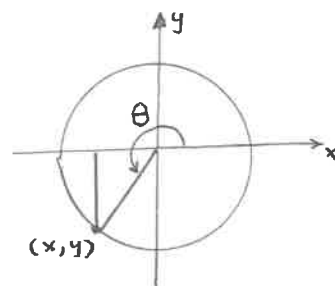
## Signs of Main Trig Functions



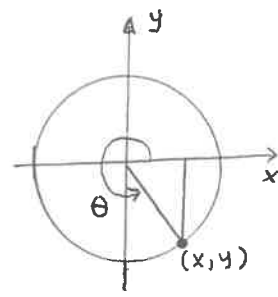
1st Quadrant  
 $\sin, \cos, \tan > 0$



2nd Quadrant  
 $\sin > 0, \cos < 0, \tan < 0$



3rd Quadrant  
 $\sin, \cos < 0, \tan > 0$



4th Quadrant  
 $\sin < 0, \cos > 0, \tan < 0$

mnemonic:

ALL	Students	Take	Calculus
all $> 0$ in 1st quad	$\sin > 0$ in 2nd quad	$\tan > 0$ in 3rd quad	$\cos > 0$ in 4th quad

# Example 27

$$\cos x \cos y = \frac{1}{2} \cos(x+y) + \frac{1}{2} \cos(x-y)$$

## Application of Sum-Difference Cos Formula to Power & Average Power

1450

$$i(t) = |I| \cos(\omega_i t + \theta_i)$$

$$+ \\ v(t) = |V| \cos(\omega_v t + \theta_v)$$

- equal by definition

$$p(t) \triangleq v(t) i(t)$$

$$= |V| \cos(\omega_v t + \theta_v) |I| \cos(\omega_i t + \theta_i)$$

$$= \frac{|V||I|}{2} \cos(\underbrace{(\omega_v + \omega_i)t + \theta_v + \theta_i}_{\text{sum of frequencies}}) + \frac{|V||I|}{2} \cos(\underbrace{(\omega_v - \omega_i)t + (\theta_v - \theta_i)}_{\text{Difference of frequencies}})$$

Now let  $\omega_v = \omega_i = \omega$

$$\Rightarrow p(t) = \frac{|V||I|}{2} \left[ \cos(\underbrace{2\omega t + \theta_v + \theta_i}_{\text{double frequency term}}) + \cos(\theta_v - \theta_i) \right]$$

$\cos(\theta_v - \theta_i)$   
constant term

If we now take the average of both sides

$$\text{i.e. } \langle f \rangle = \frac{1}{T} \int_T f(t) dt$$

↑ integral over any period for the periodic function f

$$\Rightarrow \langle p \rangle = \begin{matrix} \text{average of} \\ \text{double freq} \\ \text{term} \end{matrix} + \begin{matrix} \text{average of} \\ \text{constant} \end{matrix}$$

$$= 0 + \frac{|V||I|}{2} \cos(\theta_v - \theta_i)$$

Average power for Sinusoidal v & i

### Summary

$$i(t) = |I| \cos(\omega t + \theta_i)$$

$$+ \\ v(t) = |V| \cos(\omega t + \theta_v)$$

$$\langle p \rangle = \frac{|V||I|}{2} \cos(\theta_v - \theta_i)$$

$$p(t) = v(t) i(t) = \frac{|V||I|}{2} \left[ \cos(2\omega t + \theta_v + \theta_i) + \cos(\theta_v - \theta_i) \right]$$

↑ instantaneous power

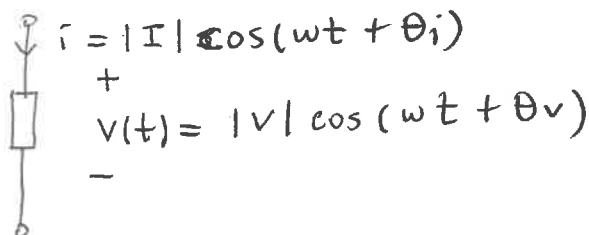
constant term

# Problem 27

(Average Power for  $R, L, C$ )

1460

Consider a device



It has been shown that

$$\langle p \rangle = \frac{|V||I|}{2} \cos(\theta_v - \theta_i) \quad \text{pg 1450}$$

a) Suppose device is a resistor ( $v = Ri$ )

Show that

$$\begin{aligned} \theta_v - \theta_i &= 0 \quad \Rightarrow \quad \cos(\theta_v - \theta_i) = 1 \\ \langle p \rangle_R &= \frac{|V||I|}{2} = \frac{R|I|^2}{2} = \frac{|V|^2}{2R} \end{aligned}$$

b) Suppose device is a capacitor ( $i = C \frac{dv}{dt}$ )

voltage lags current by  $90^\circ$

$$\begin{aligned} I &= sC V \Rightarrow \frac{V}{I} = \frac{1}{sC} \\ &\Rightarrow \frac{V}{I} = \frac{1}{j\omega C} \end{aligned}$$

$$\begin{aligned} \theta_v - \theta_i &= -90^\circ \\ \cos(\theta_v - \theta_i) &= 0 \\ \langle p_c \rangle &= 0 \end{aligned}$$

c) Suppose device is an inductor ( $v = L \frac{di}{dt}$ )

voltage leads current by  $90^\circ$

$$\begin{aligned} V &= (sL) I \Rightarrow \frac{V}{I} = sL \\ &\Rightarrow \frac{V}{I} = j\omega L \end{aligned}$$

$$\begin{aligned} \theta_v - \theta_i &= +90^\circ \\ \cos(\theta_v - \theta_i) &= 0 \\ \langle p_L \rangle &= 0 \end{aligned}$$

## Example 28

Mastering  
(Complex Numbers!) 1470

Note: Complex #'s were introduced by Cardano in 1545 while he was finding the roots of a cubic.



1st Advice:

Draw lots of pictures!

This is critical to mastering complex #'s & using them proficiently when analyzing dynamical systems.

Notation:

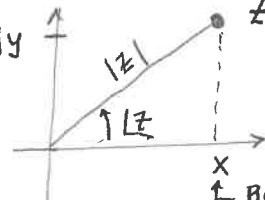
We will write complex #'s as =

often used  
by  
mathematicians

$$z = x + jy$$

(rectangular form)

$$j \operatorname{Im} z \rightarrow jy$$



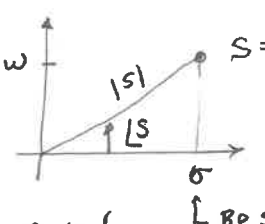
$$z = |z|e^{j\theta}$$

polar form  
complex  
z-plane

often used  
by  
engineers

$$s = \sigma + j\omega$$

$$j \operatorname{Im} s \rightarrow j\omega$$



$$s = |s|e^{j\theta}$$

polar form  
complex  
s-plane

Note: Can & will be associated with exponential sinusoid  $Ae^{-\sigma t} \cos(\omega t + \theta)$

Lets start with some basics.

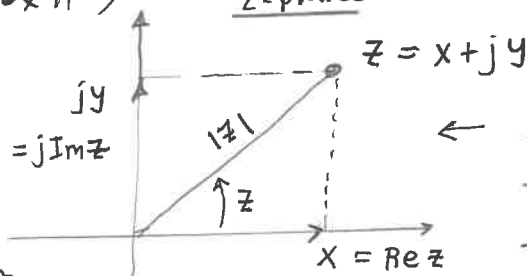
# Example 28

(Mastering Complex #'s)

complex  
z-plane

1480

Consider the complex # =  $j \triangleq \sqrt{-1}$



this picture shows a 1st quadrant angle

rectangular form of z

$$z = x + jy$$

equals by definition

$$\text{Re } z \triangleq x = |z| \cos Lz$$

$$\text{Im } z \triangleq y = |z| \sin Lz$$

always true

$$|z| = \sqrt{(\text{Re } z)^2 + (\text{Im } z)^2} = \sqrt{x^2 + y^2}$$

from picture

Pythagorean Theorem

Convention =

Always measured with respect to positive "x-axis"

$$Lz = \tan^{-1}\left(\frac{y}{x}\right)$$

from 1st quadrant angle picture shown & basic trig

NOT always true!

always true

$$z = |z| e^{jLz}$$

polar form of z

Note:

Im z is NOT jy don't EVER make this mistake!

Note:

We will see below that this does NOT hold for any sign of x & y!

It is true (i.e.  $Lz = \tan^{-1}(\frac{y}{x})$ ) for

1st quad angles ( $x, y > 0$ )

4th quad angles ( $x > 0, y < 0$ )

It is not true for

2nd quad angles ( $x < 0, y > 0$ )

3rd quad angles ( $x, y < 0$ )

... here we go on our complex # journey...

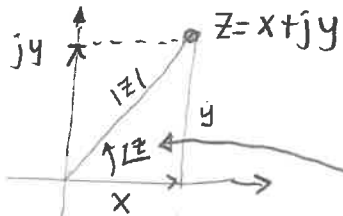
... we begin by examining complex #'s in each quadrant.

## Example 28

(Mastering  
Complex  
#s)This slide show the importance  
of pictures... for understanding  $\angle z$ 1st Quadrant ( $x, y > 0$ )

$$z = x + jy$$

rectangular form



$$\operatorname{Re} z = x = |z| \cos \angle z$$

$$\operatorname{Im} z = y = |z| \sin \angle z$$

$$|z| = \sqrt{x^2 + y^2}$$

$$\angle z = \tan^{-1}\left(\frac{y}{x}\right)$$

$$z = |z| e^{j\angle z}$$

$$= \sqrt{x^2 + y^2} e^{j(\tan^{-1}(\frac{y}{x}))}$$

polar form

2nd Quadrant ( $x < 0, y > 0$ )

$$z = x + jy = -|x| + jy$$



$$\operatorname{Re} z = x = -|x| = |z| \cos \angle z$$

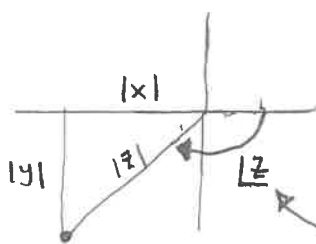
$$\operatorname{Im} z = y = |z| \sin \angle z$$

$$|z| = \sqrt{x^2 + y^2}$$

$$\angle z = 180 - \tan^{-1}\left(\frac{y}{|x|}\right)$$

$$z = |z| e^{j\angle z}$$

$$= \sqrt{x^2 + y^2} e^{j(180 - \tan^{-1}(\frac{y}{|x|}))}$$

3rd Quadrant ( $x, y < 0$ )

$$z = x + jy = -|x| - j|y|$$

(convention =  
use the "smaller" angle)

$$\operatorname{Re} z = x = -|x| = |z| \cos \angle z$$

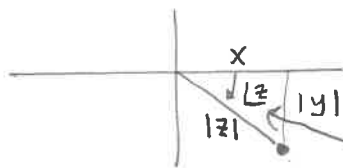
$$\operatorname{Im} z = y = -|y| = |z| \sin \angle z$$

$$|z| = \sqrt{x^2 + y^2}$$

$$\angle z = -180 + \tan^{-1}\left(\frac{|y|}{|x|}\right)$$

$$z = |z| e^{j\angle z}$$

$$= \sqrt{x^2 + y^2} e^{j(-180 + \tan^{-1}(\frac{|y|}{|x|}))}$$

4th Quadrant ( $x > 0, y < 0$ )

$$z = x + jy = x - j|y|$$

$$\operatorname{Re} z = x$$

$$\operatorname{Im} z = y = -|y|$$

$$|z| = \sqrt{x^2 + y^2}$$

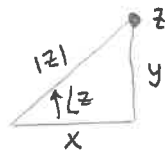
$$\angle z = -\tan^{-1}\left(\frac{|y|}{x}\right)$$

Note:  $\angle z = \tan^{-1}(\frac{y}{x})$  only for 1st & 4th quadrant angles!

$$z = |z| e^{j\angle z} = \sqrt{x^2 + y^2} e^{-j \tan^{-1}(\frac{|y|}{x})}$$

# Summary of Results That Always Hold

Let  $z = x + jy$



(for any  $x, y$ )

← drawn for  $x, y > 0$   
(1st quadrant angle)

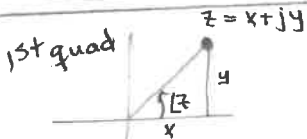
$$\operatorname{Re} z = |z| \cos Lz = x$$

$$\operatorname{Im} z = |z| \sin Lz = y$$

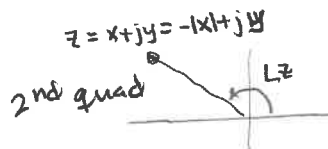
$$|z| = \sqrt{(\operatorname{Re} z)^2 + (\operatorname{Im} z)^2} \\ = \sqrt{x^2 + y^2}$$

$$z = x + jy = |z| \cos Lz + j |z| \sin Lz = |z| e^{jLz}$$

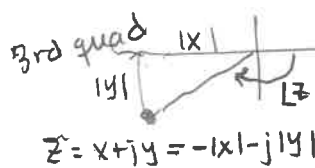
For:



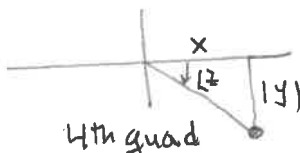
$$Lz = \tan^{-1}\left(\frac{y}{x}\right)$$



$$Lz = 180 - \tan^{-1}\left(\frac{y}{|x|}\right)$$



$$Lz = -180 + \tan^{-1}\left(\frac{|y|}{|x|}\right)$$



$$Lz = -\tan^{-1}\left(\frac{|y|}{x}\right)$$

Warning:

← Draw pictures to get the angles right!

Recall:

$$\bar{z} \triangleq |z| e^{-jLz} = \operatorname{Re} z - j \operatorname{Im} z = x - jy$$

conjugate of  $z$

can be shown with some arithmetic



## Example 28

(Mastering complex #'s)

1510

### Arithmetic Operations:

$$\text{Let } z_1 = x_1 + jy_1 = |z_1| e^{j\angle z_1}$$

$$z_2 = x_2 + jy_2 = |z_2| e^{j\angle z_2}$$

#### Addition

$$\begin{aligned} z_1 + z_2 &= (x_1 + jy_1) + (x_2 + jy_2) \\ &= (x_1 + x_2) + j(y_1 + y_2) \end{aligned}$$

Note: Rectangular forms facilitate addition!

Using polar forms:

$$z_1 + z_2 = |z_1| e^{j\angle z_1} + |z_2| e^{j\angle z_2}$$

$$= (|z_1| \cos \angle z_1 + j |z_1| \sin \angle z_1) + (|z_2| \cos \angle z_2 + j |z_2| \sin \angle z_2)$$

$$= (x_1 + jy_1) + (x_2 + jy_2)$$

$$= (x_1 + x_2) + j(y_1 + y_2)$$

... just need to

add real parts to get new real part  
" imag " " " " imag "


using polar forms takes more work for addition!

angles add

#### Multiplication

$$z_1 z_2 = (|z_1| e^{j\angle z_1}) (|z_2| e^{j\angle z_2}) = |z_1| |z_2| e^{j(\angle z_1 + \angle z_2)}$$

magnitudes multiply

Here, the polar forms are the way to go! 

Using rectangular forms:

$$z_1 z_2 = (x_1 + jy_1)(x_2 + jy_2)$$

$$= (x_1)(x_2 + jy_2) + (jy_1)(x_2 + jy_2)$$

$$= x_1 x_2 + jx_1 y_2 + jy_1 x_2 + (j)(j) y_1 y_2$$

$$= (x_1 x_2 - y_1 y_2) + j(x_1 y_2 + x_2 y_1)$$

Use distributive property of multiplication over addition!

$$j^2 = -1$$

(just gathered real + imag parts)

This is much more work!



It can be shown (after a lot of algebra) that

$$(x_1 x_2 - y_1 y_2) + j(x_1 y_2 + x_2 y_1) = |z_1| |z_2| e^{j(\angle z_1 + \angle z_2)}$$

How about division - - -

# Example 28

(Mastering complex #'s)

## Division

$$\frac{z_1}{z_2} = \frac{|z_1| e^{j\angle z_1}}{|z_2| e^{j\angle z_2}} = \frac{|z_1|}{|z_2|} e^{j(\angle z_1 - \angle z_2)}$$

angle (top)  
- angle (bottom)

1520

EASY!

(magnitude of top) / (magnitude of bottom)

Here, the polar forms are the way to go!

remember this trick

Using rectangular forms =

$$\begin{aligned} \frac{z_1}{z_2} &= \left( \frac{x_1 + jy_1}{x_2 + jy_2} \right) = \left( \frac{x_1 + jy_1}{x_2 + jy_2} \right) \left( \frac{x_2 - jy_2}{x_2 - jy_2} \right) \\ &= \frac{x_1 x_2 - jx_1 y_2 + jy_1 x_2 - j^2 y_1 y_2}{x_2^2 - jx_2 y_2 + jy_2 x_2 - j^2 y_2^2} \\ &= \frac{(x_1 x_2 + y_1 y_2) + j(-x_1 y_2 + x_2 y_1)}{x_2^2 + y_2^2} \\ &= \left( \frac{x_1 x_2 + y_1 y_2}{x_2^2 + y_2^2} \right) + j \left( \frac{-x_1 y_2 + x_2 y_1}{x_2^2 + y_2^2} \right) \end{aligned}$$

after a lot of algebra one can show that this

$$= \frac{|z_1|}{|z_2|} e^{j(\angle z_1 - \angle z_2)}$$

This is  
much  
more  
work!



# Example 28

(Mastering complex #'s)

1530

Here are

Some simple complex #'s = (assume  $x > 0$ )

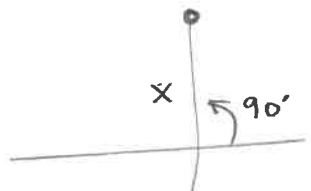
$$x = x e^{j0^\circ}$$



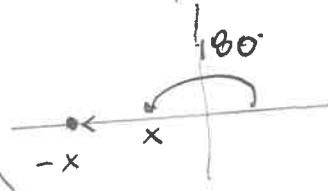
Angle of a positive # is  $0^\circ$   
( $\pm$  any integer multiple of  $360^\circ$ ... but it is convention to take  $0^\circ$  as best answer!)

Magnitude of a positive # is simply the #!  
Angle of a positive # is  $0^\circ$

$$jx = x e^{j90^\circ}$$



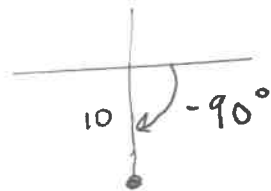
$$-x = x e^{j180^\circ}$$



(angle here can also be taken as  $-180^\circ$  or  $180^\circ \pm$  any integer multiple of  $360^\circ$ ... but it is convention to take  $180^\circ$  as best answer!)

Magnitude of a negative # is simply  $|\#|$  (absolute value of #)  
Angle of a negative # is  $180^\circ$

$$-jx = x e^{-j90^\circ}$$



Message on Approximation =

$$z + \Delta \cong z \quad \text{when} \quad |\Delta| < \frac{1}{10} |z|$$

e.g.  $j1 + 0.1 \cong j1 = 1 e^{j90^\circ}$   
 $10 \pm j1 \cong 10 = 10 e^{j0^\circ}$

$-j1 + 0.1 \cong -j1 = 1 e^{-j90^\circ}$   
 $-100 \pm j10 \cong -100 = 100 e^{j180^\circ}$

# Example 28

(Mastering Complex #5)

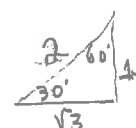
1540

lets take our complex # picture for a ride  
 ... to see how they can be used in practice  
 (i.e. analysis of dynamical systems)

$$Z = \frac{(\sqrt{3} + j1)(-1 + j1)(-4 - j3)(100 + j1)}{(j10)(6 - j8)(0.1 - j1)(-9 + j10)}$$

We want to find  $|Z|$ ,  $\angle Z$ ,  $\text{Re} Z$ ,  $\text{Im} Z$  ... (approximate when it makes sense to do so!)

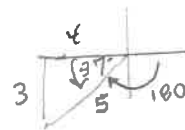
Lets begin by drawing pictures:



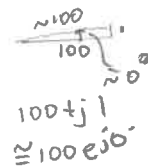
$$\sqrt{3} + j1 = 2e^{j30^\circ}$$



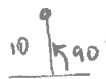
$$-1 + j1 = \sqrt{2}e^{j135^\circ}$$



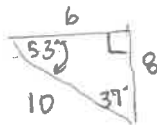
$$-4 - j3 = 5e^{-j143^\circ}$$



$$100 + j1 \approx 100e^{j0^\circ}$$



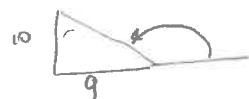
$$j10 = 10e^{j90^\circ}$$



$$6 - j8 = 10e^{-j53^\circ}$$



$$0.1 - j1 \approx -j1 = 1e^{-j90^\circ}$$



$$-9 + j10 = \sqrt{81 + 100} \approx 10\sqrt{2}$$

$$\angle = 180^\circ - \tan^{-1}\left(\frac{10}{9}\right) \text{ (near } 135^\circ)$$

approximate because we have approximated!

$$|Z| = \frac{|top|}{|bottom|} \approx \frac{(2)(\sqrt{2})(5)(100)}{(10)(10)(1)(\sqrt{81+100})}$$

$\uparrow$  approx
 $\uparrow$  approx

$$\angle Z = \angle_{top} - \angle_{bottom} = [(30^\circ) + (135^\circ) + (-143^\circ) + (0^\circ)] - [(90^\circ) + (-53^\circ) + (-90^\circ) + (180^\circ - \tan^{-1}(\frac{10}{9}))]$$

# Example 28

(Mastering Complex #'s)

1550

Consider

$$H(s) = \frac{(s+1)(s-2)(3-s)(s^2+2s+2)}{s^2(s^2+s+1)(s^2-8s+25)}$$

Compute  $|H(j\omega)|$ ,  $\angle H(j\omega)$  for each  $\omega$  below

(approximate when it makes sense to do so)

$\omega = 0.1$

$$H(j0.1) \approx \frac{(1e^{j0^\circ})(2e^{j180^\circ})(3e^{j0^\circ})(2e^{j0^\circ})}{(1e^{j90^\circ})^2(1e^{j0^\circ})(25e^{j0^\circ})}$$

$$\approx \frac{(1)(2)(3)(2)}{(1^2)(1)(25)} e^{j(180^\circ - 2(90^\circ))}$$

$\uparrow \sim |H(j0.1)|$ 
 $\uparrow \sim \angle H(j0.1)$

$\omega = 1$

$$H(j1) = \frac{(j1+1)(j1-2)(3-j1)(-1+j2+2)}{(1e^{j90^\circ})^2(-1+j1+1)(-1-j8+25)}$$

$$= \frac{(1+j1)(-2+j1)(3-j1)(1+j2)}{(1e^{j2(90^\circ)})(j1)(24-j8)}$$

$$= \frac{(\sqrt{2}e^{j45^\circ})(\sqrt{4+1}e^{j(180-\tan^{-1}(\frac{1}{2}))})(\sqrt{9+1}e^{-j\tan^{-1}(\frac{1}{3})})(\sqrt{1+4}e^{j\tan^{-1}(\frac{2}{1})})}{(1e^{j2(90^\circ)})(1e^{j90^\circ})(\sqrt{24^2+64}e^{-j\tan^{-1}(\frac{8}{24})})}$$

$\tan^{-1}(\frac{8}{24})$

$$|H(j1)| = \frac{(\sqrt{2})(\sqrt{4+1})(\sqrt{9+1})(\sqrt{1+4})}{(1)(1)(\sqrt{24^2+64})}$$

$$\angle H(j1) = \angle \text{top} - \angle \text{bottom}$$

$$= [45^\circ + (180 - \tan^{-1}(\frac{1}{2})) - (\tan^{-1}(\frac{1}{3})) + \tan^{-1}(\frac{2}{1})] - [2(90^\circ) + 90^\circ]$$

# Example 28

(Mastering complex #'s)

1550

$$\omega = 5$$

$$\begin{aligned}
 H(j5) &= \frac{(j5+1)(j5-2)(3-j5)(-25+j10+2)}{(5e^{j90^\circ})^2(-25+j5+1)(-25-j40+25)} \\
 &= \frac{\begin{array}{c} \triangle 5 \\ 1 \end{array} \begin{array}{c} \triangle 5 \\ 2 \end{array} \begin{array}{c} \triangle 5 \\ 3 \end{array} \begin{array}{c} \triangle 10 \\ 23 \end{array}}{(25e^{j2(90^\circ)}) \begin{array}{c} \triangle 5 \\ 24 \end{array} \begin{array}{c} \triangle 40 \\ 40 \end{array} \begin{array}{c} \triangle 40 \\ 40 \end{array})} \\
 &= \frac{(\sqrt{1+25} e^{j \tan^{-1}(\frac{5}{1})}) (\sqrt{4+25} e^{j(180^\circ - \tan^{-1}(\frac{5}{2}))}) (\sqrt{9+25} e^{j \tan^{-1}(\frac{5}{3})}) (\sqrt{23^2+100} e^{j(180^\circ - \tan^{-1}(\frac{10}{23}))})}{(25e^{j2(90^\circ)}) (\sqrt{24^2+25} e^{j(180^\circ - \tan^{-1}(\frac{5}{24}))}) (40e^{-j90^\circ})}
 \end{aligned}$$

$$|H(j5)| = \frac{(\sqrt{1+25})(\sqrt{4+25})(\sqrt{9+25})(\sqrt{23^2+100})}{(25)(\sqrt{24^2+25})(40)} \leftarrow \frac{|top|}{|bottom|}$$

$$\angle H(j5) = \angle top - \angle bottom$$

$$\begin{aligned}
 &= [\tan^{-1}(\frac{5}{1}) + (180^\circ - \tan^{-1}(\frac{5}{2}))] + (-\tan^{-1}(\frac{5}{3}) + (180^\circ - \tan^{-1}(\frac{10}{23}))) \\
 &- [2(90^\circ) + (180^\circ - \tan^{-1}(\frac{5}{24})) + (-90^\circ)]
 \end{aligned}$$

# Example 28

(Mastering complex #'s)

1570

$$\omega = 10$$

$$\begin{aligned}
 H(j10) &= \frac{(j10 + 1)(j10 - 2)(3 - j10)(-100 + j20 + 2)}{(10e^{j90^\circ})^2 (-100 + j10 + 1)(-100 - j80 + 25)} \\
 &\approx \frac{10e^{j90^\circ} \cdot 10e^{j90^\circ} \cdot 10e^{j90^\circ} \cdot 10e^{j90^\circ} \cdot 10e^{j90^\circ}}{(j10 + 0)(-2 + j10)(3 - j10)(-100 + j20 + 0)} \\
 &= \frac{(100e^{j2(90^\circ)})((-100) + 0 + 0)(-75 - j80)}{(100e^{j180^\circ})(100e^{j180^\circ})(\sqrt{75^2 + 80^2}e^{j(-180 + \tan^{-1}(\frac{80}{75}))})} \\
 &\approx \frac{(10e^{j90^\circ})(\sqrt{4+100}e^{j(180 - \tan^{-1}(\frac{10}{2}))})(\sqrt{9+100}e^{-j\tan^{-1}(\frac{10}{3})})(\sqrt{10^4+400}e^{j(180 - \tan^{-1}(\frac{20}{100}))})}{(100e^{j2(90^\circ)})(100e^{j180^\circ})(\sqrt{75^2+80^2}e^{j(-180 + \tan^{-1}(\frac{80}{75}))})}
 \end{aligned}$$

$$|H(j10)| = \frac{|top|}{|bottom|} = \frac{(10)(\sqrt{4+100})(\sqrt{9+100})(\sqrt{10^4+400})}{(100)(100)(\sqrt{75^2+80^2})}$$

$$\begin{aligned}
 \angle H(j10) &= \angle top - \angle bottom \\
 &= [90^\circ + (180 - \tan^{-1}(\frac{10}{2})) + (-\tan^{-1}(\frac{10}{3})) + (180 - \tan^{-1}(\frac{20}{100}))] \\
 &\quad - [2(90^\circ) + (180^\circ) + (-180 + \tan^{-1}(\frac{80}{75}))]
 \end{aligned}$$

# Example 28

(Mastering complex #'s)

1580

$$\omega = 1000$$

$$H(j10^3) = \frac{(j10^3 + 1)(j10^3 - 2)(3 - j10^3)(-10^6 + j2 \times 10^3 + 2)}{(10^3 e^{j90^\circ})^2 (-10^6 + j10^3 + 1)(-10^6 - j8 \times 10^3 + 25)}$$

$$\approx \frac{(j10^3)(j10^3)(-j10^3)(-10^6)}{(10^6 e^{j2(90^\circ)})(-10^6)(-10^6)}$$

$$\approx \frac{(10^3 e^{j90^\circ})(10^3 e^{j90^\circ})(10^3 e^{-j90^\circ})(10^6 e^{j180^\circ})}{(10^6 e^{j2(90^\circ)})(10^6 e^{j180^\circ})(10^6 e^{j180^\circ})}$$

$$|H(j10^3)| = \frac{|top|}{|bottom|} \approx \frac{(10^3)(10^3)(10^3)(10^6)}{(10^6)(10^6)(10^6)} = 10^{-3}$$

$$\angle H(j10^3) = \angle top - \angle bottom \approx [90 + 90 - 90 + 180] - [2(90) + 180 + 180] = -270^\circ$$

Note: For  $s$  large

$$H(s) \approx \frac{(s)(s)(-s)(s^2)}{s^2(s^2)(s^2)} = \frac{-s^5}{s^6} = \frac{-1}{s}$$

from which  $H(j10^3) \approx \frac{-1}{j10^3} = \frac{1e^{j180^\circ}}{10^3 e^{j90^\circ}} = 10^{-3} e^{j90^\circ} = 10^{-3} e^{-j270^\circ}$

$$\Rightarrow |H(j10^3)| \approx 10^{-3}$$

$$\angle H(j10^3) \approx 90^\circ \text{ or } -270^\circ !$$



too much work

look here!



# Example 28

(Mastering complex #'s)

1590

$$H(s) = \frac{(s+1)(s-2)(3-s)(s^2+2s+2)}{s^2(s^2+s+1)(s^2-8s+25)}$$

Lets compute  $H(j\omega)$

$$H(j\omega) = \frac{\begin{array}{c} \triangle^w \\ 1 \end{array} \begin{array}{c} w \triangle \\ 2 \end{array} \begin{array}{c} 3 \\ \triangle^w \end{array} (2-w^2+j2w)}{\underbrace{(we^{j90^\circ})^2}_{w \downarrow 180^\circ} (1-w^2+jw) (25-w^2-j8w)}$$

From this, we have

$$|H(j\omega)| = \frac{|top|}{|bottom|} = \frac{(\sqrt{1+w^2})(\sqrt{4+w^2})(\sqrt{9+w^2})(\sqrt{(2-w^2)^2+4w^2})}{(w^2)(\sqrt{(1-w^2)^2+w^2})(\sqrt{(25-w^2)^2+64w^2})}$$

$$\angle H(j\omega) = \angle top - \angle bottom$$

$$\begin{aligned} \angle top &= \angle 1+jw + \angle -2+jw + \angle 3-jw + \angle 2-w^2+j2w \\ &= \tan^{-1}\left(\frac{w}{1}\right) + \left[180 - \tan^{-1}\left(\frac{w}{2}\right)\right] - \tan^{-1}\left(\frac{w}{3}\right) + \angle 2-w^2+j2w \end{aligned}$$

$$\angle 2-w^2+j2w = \begin{cases} \tan^{-1}\left(\frac{2w}{2-w^2}\right) & \begin{array}{c} \triangle \\ 2-w^2 \end{array} \begin{array}{c} 2w \end{array} \quad \begin{array}{c} 2 > w^2 \\ (\sqrt{2} > w) \end{array} \\ 180^\circ - \tan^{-1}\left(\frac{2w}{w^2-2}\right) & \begin{array}{c} 2w \\ \triangle \\ w^2-2 \end{array} \quad \begin{array}{c} 2 < w^2 \\ (\sqrt{2} < w) \end{array} \end{cases}$$

$$\angle bottom = 2(90^\circ) + \angle 1-w^2+jw + \angle 25-w^2-j8w$$

lets now address these 2 terms

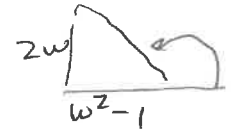
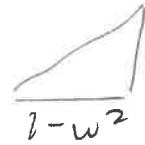
# Example 28

(Mastering Complex #'s)

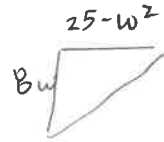
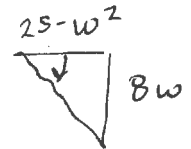
1600

Mon  
2w 3/18/24  
(w < 1)

$$\frac{1-w^2+j2w}{1-w^2} = \begin{cases} \tan^{-1}\left(\frac{2w}{1-w^2}\right) \\ 180^\circ - \tan^{-1}\left(\frac{2w}{w^2-1}\right) \end{cases}$$



$$\frac{1}{25-w^2-j8w} = \begin{cases} -\tan^{-1}\left(\frac{8w}{25-w^2}\right) \\ -180^\circ + \tan^{-1}\left(\frac{8w}{25-w^2}\right) \end{cases}$$



(w < 5)

(w > 5)

## Example 28

(Mastering complex #'s)

1610

Mon 3-18-24

How is it that  $z = x + jy$

can be written in polar form  $z = |z| e^{j\angle z}$ ?

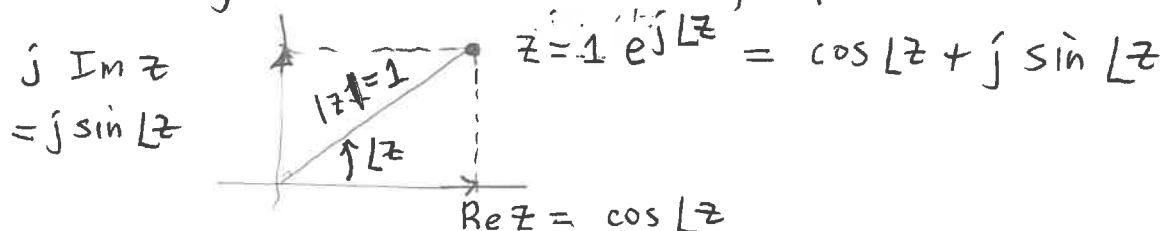
This great fact we owe to the great Euler (1748).

$$\begin{aligned} z = x + jy &= \operatorname{Re} z + j \operatorname{Im} z \\ &= |z| \cos \angle z + j |z| \sin \angle z \\ &= |z| [\cos \angle z + j \sin \angle z] \\ &= |z| e^{j \angle z} \end{aligned}$$

It was Euler that 1<sup>st</sup> showed (1748, via series) that

$$e^{j \angle z} = \cos \angle z + j \sin \angle z \quad \leftarrow \text{Euler's Identity}$$

While he used series to prove this, it follows intuitively from the following picture =



# Example 23

(Mastering complex #'s)

1620

From Euler's identity we also have

$$\begin{aligned} e^{-jLz} &= \cos(-Lz) + j \sin(-Lz) \\ &= \cos Lz - j \sin Lz \end{aligned}$$

since

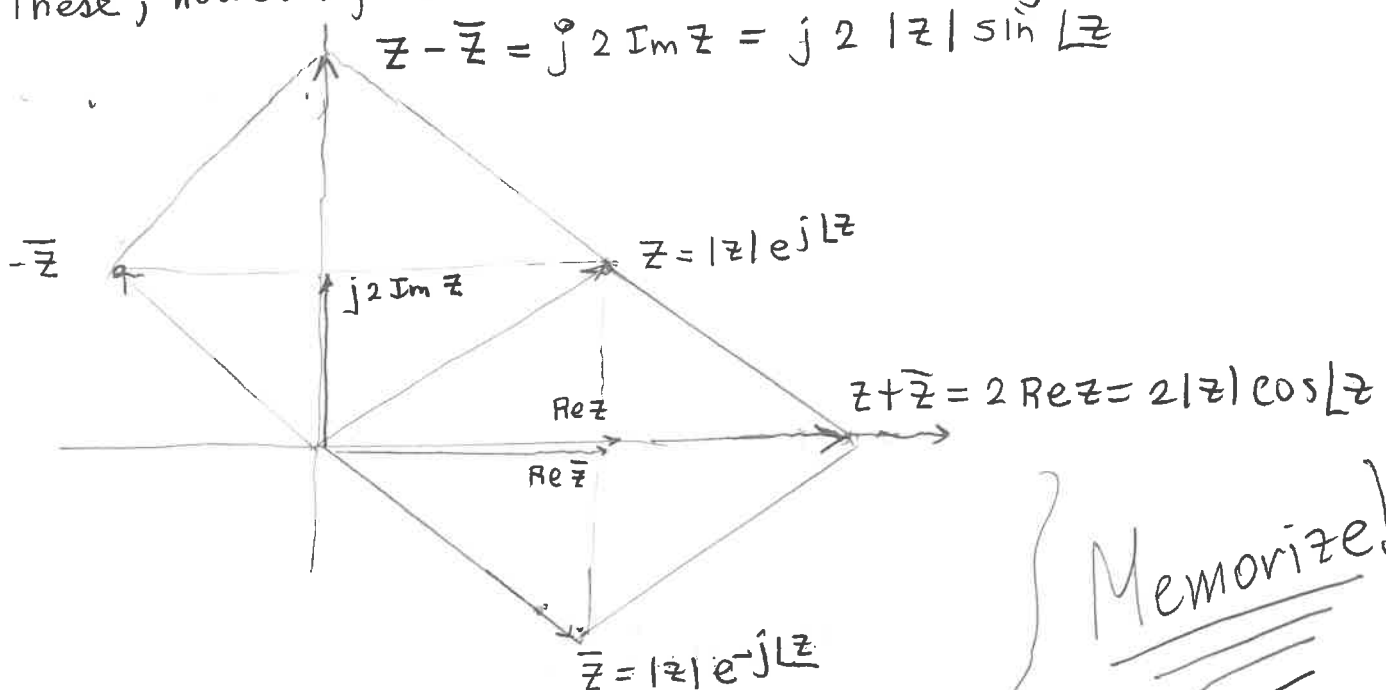
$$\begin{aligned} \cos(-x) &= \cos x \\ \sin(-x) &= -\sin x \end{aligned}$$

From the above we then get

$$e^{jLz} + e^{-jLz} = 2 \cos Lz = 2 \operatorname{Re} e^{jLz}$$

$$e^{jLz} - e^{-jLz} = j 2 \sin Lz = j 2 \operatorname{Im} e^{jLz}$$

These, however, follow from the following <sup>compelling</sup> picture =



$$z + \bar{z} = 2 \operatorname{Re} z = 2 |z| \cos Lz$$

$$z - \bar{z} = j 2 \operatorname{Im} z = j 2 |z| \sin Lz$$

Memorize!

Euler  
Identities

### Example 28

(Mustaring complex #'s)

1630

To see how the above Euler identities can be applied to sinusoids, let

$$\begin{aligned} z &= A e^{(\sigma + j\omega)t} \\ &= |A| e^{j\angle A} e^{\sigma t} e^{j\omega t} \\ &= \underbrace{|A| e^{\sigma t}}_{|z|} e^{j(\underbrace{\omega t + \angle A}_{\angle z})} \end{aligned}$$

From this it follows that

$$\begin{aligned} |A| e^{\sigma t} \cos(\omega t + \angle A) &= |z| \cos \angle z \\ &= \operatorname{Re} z \\ &= \frac{z + \bar{z}}{2} \end{aligned}$$

↙

$$\begin{aligned} |A| e^{\sigma t} \sin(\omega t + \angle A) &= |z| \sin \angle z \\ &= \operatorname{Im} z \\ &= \frac{z - \bar{z}}{j2} \end{aligned}$$

## Example 28

(Mastering Complex #'s)

1640

Now lets show how the above can be used to add sinusoids!

Consider

$$f(t) = A_1 \cos(\omega t + \theta_1) + A_2 \cos(\omega t + \theta_2) + A_3 \cos(\omega t + \theta_3)$$

We want to add these to get

$$f(t) = A \cos(\omega t + \theta)$$

lets find  $A$  &  $\theta$ . (using complex #'s --- NO TRIG!)

$$f(t) = \text{Re} \left[ A_1 e^{j(\omega t + \theta_1)} + A_2 e^{j(\omega t + \theta_2)} + A_3 e^{j(\omega t + \theta_3)} \right]$$

$$= \text{Re} \left\{ (A_1 e^{j\theta_1} + A_2 e^{j\theta_2} + A_3 e^{j\theta_3}) e^{j\omega t} \right\}$$

let this be  $A e^{j\theta}$

$$= \text{Re} \left\{ A e^{j(\omega t + \theta)} \right\}$$

$$= A \cos(\omega t + \theta)$$

To find  $A$  &  $\theta$  we just need to solve

$$A e^{j\theta} = A_1 e^{j\theta_1} + A_2 e^{j\theta_2} + A_3 e^{j\theta_3}$$

i.e. add this, find magnitude & angle

$A = \text{magnitude}$     $\theta = \text{angle!}$

# Problem 28

1650

1

Find  $A$  &  $\theta$  in  $f(t) = A \cos(\omega t + \theta)$

where

$$f(t) = 1 \cos(\omega t + 30^\circ) + 2 \cos(\omega t + 45^\circ) + 3 \cos(\omega t + 60^\circ)$$

Hint:

see pg 1640

add:

$$z = 1e^{j30} + 2e^{j45} + 3e^{j60}$$

Find  $|z|$  &  $\angle z$

2

Consider

$$H(s) = \frac{s^3 (s+1) (10-s) (s^2+8s+25)}{(s+3) (s^2-s-1) (s^2-6s+10)}$$

a) Compute  $|H(j\omega)|$ ,  $\angle H(j\omega)$

Hint = Draw pictures

See

pages 1590-1600

b) Estimate  $|H(j\omega)|$  &  $\angle H(j\omega)$  for  $\omega = 0.1$

c) " " " "  $\omega = 1$

d) " " " "  $\omega = 100$

3

Consider  $z = \frac{(-1+j1)^2 (-\sqrt{3}-j1) (4-j3)^3 (6e^{j90^\circ}) (8)}{(j2)^3 (2+j2\sqrt{3}) (-6+j8)^4 (-4) (-2-j3)}$

Determine  $|z|$ ,  $\angle z$ ,  $\text{Re } z$ ,  $\text{Im } z$ .

# Example 29

## Transfer Function (Frequency Responses)

1660

For each of the following transfer functions compute  
 $\rightarrow$  plot the magnitude response  $|H(j\omega)|$  and the  
 phase response  $\angle H(j\omega)$ .

Note: This is useful because of the  
 so-called

Method of the Transfer Function  
 (MOTF) !

1

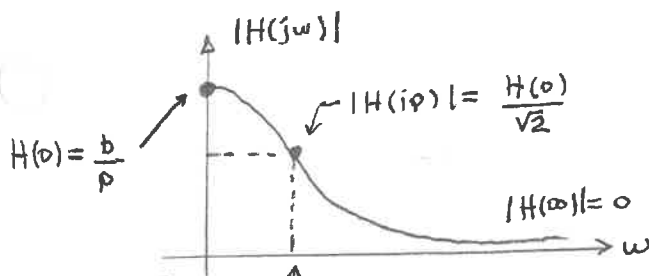
$$H(s) = \frac{b}{s+p}$$

$$b, p > 0$$

$$H(j\omega) = \frac{b}{j\omega + p}$$

$$\frac{p^2 + \omega^2}{p} \quad \tan^{-1}\left(\frac{\omega}{p}\right)$$

$$|H(j\omega)| = \frac{|top|}{|bottom|} = \frac{b}{\sqrt{\omega^2 + p^2}}$$



$$\omega_{3dB} = p \quad \text{since} \quad 20 \log_{10} |H(jp)| = 20 \log_{10} \left( \frac{H(0)}{\sqrt{2}} \right) = 20 \log_{10} H(0) - 20 \log_{10} \sqrt{2} = 20 \log_{10} H(0) - 3$$

Note

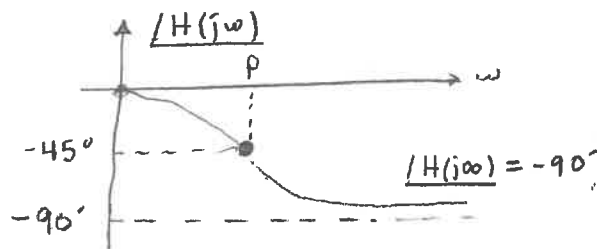
$$H(0) = \frac{b}{p}$$

$$H(jp) = \frac{b}{jp+p} = \frac{b/p}{1+j} = \frac{H(0)}{\sqrt{2}} e^{j45^\circ}$$

$$H(j\omega) \underset{\omega \text{ large}}{\approx} \frac{b}{j\omega} = \frac{b}{\omega} e^{j90^\circ} = \frac{H(0)}{\sqrt{2}} e^{-j45^\circ} = \frac{b}{\omega} e^{-j90^\circ}$$

$$H(\infty) = 0$$

$$\begin{aligned} \angle H(j\omega) &= \angle top - \angle bottom \\ &= 0 - \tan^{-1}\left(\frac{\omega}{p}\right) \\ &= -\tan^{-1}\left(\frac{\omega}{p}\right) \end{aligned}$$



Because of this magnitude response,  
 H is called a low pass filter (LPF).



# Example 29

1670

2

$$H(s) = \frac{bs}{s+p}$$

$$b, p > 0$$

$$H(j\omega) = \frac{bj\omega}{j\omega + p}$$

$$\tan^{-1}\left(\frac{\omega}{p}\right)$$

$$|H(j\omega)| = \frac{|top|}{|bottom|} = \frac{b\omega}{\sqrt{\omega^2 + p^2}}$$

Note:

$$H(0) = 0$$

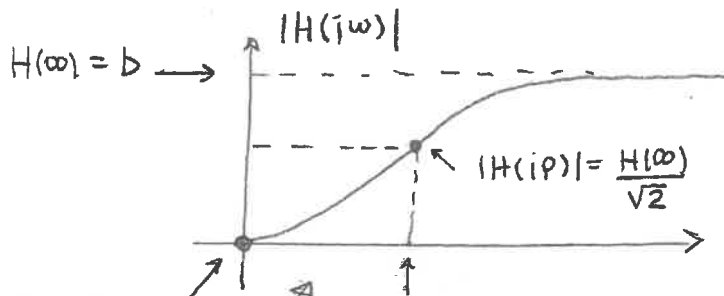
$$H(\infty) = b$$

$$H(jp) = \frac{bjp}{jp + p}$$

$$= \frac{j b}{1 + j1}$$

$$= \frac{be^{j90^\circ}}{\sqrt{2}e^{j45^\circ}}$$

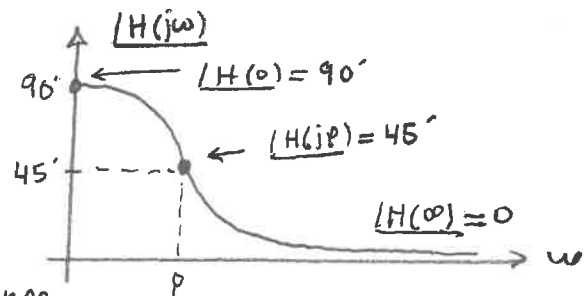
$$= \frac{H(\infty)}{\sqrt{2}} e^{j(90-45^\circ)}$$



$$H(0) = 0$$

$$\begin{aligned} \omega_{3dB} = p \text{ since } 20 \log_{10} |H(jp)| \\ &= 20 \log_{10} H(\infty) - 20 \log_{10} \sqrt{2} \\ &= 20 \log_{10} H(\infty) - 3 \end{aligned}$$

$$\begin{aligned} \angle H(j\omega) &= \angle top - \angle bottom \\ &= 90^\circ - \tan^{-1}\left(\frac{\omega}{p}\right) \end{aligned}$$



Because of this magnitude response,

$H$  is called a high pass filter (HPF).

# Example 29

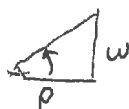
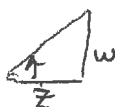
1680

3

$$H(s) = g \left[ \frac{s+z}{s+p} \right]$$

$$g, z, p > 0$$

$$H(j\omega) = g \left[ \frac{j\omega+z}{j\omega+p} \right]$$

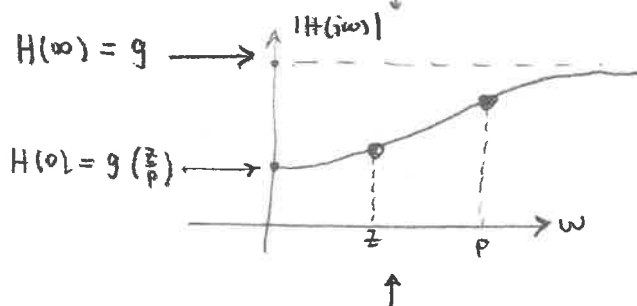


$$|H(j\omega)| = \frac{|\text{top}|}{|\text{bottom}|} = g \frac{\sqrt{\omega^2 + z^2}}{\sqrt{\omega^2 + p^2}}$$

Note:  $H(0) = g\left(\frac{z}{p}\right)$   $H(\infty) = g$

Suppose

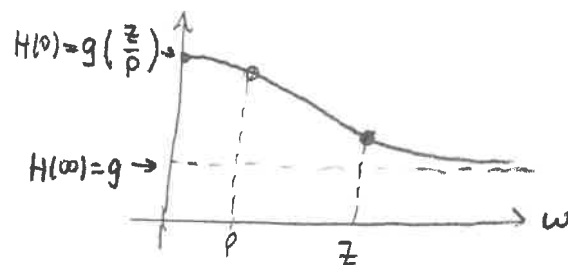
$$z < p$$



H is a high pass filter (HPF)  
when  $z < p$

Suppose

$$z > p$$



H is a low pass filter (LPF)  
when  $z > p$

$$\angle H(j\omega) = \angle \text{top} - \angle \text{bottom} = \tan^{-1}\left(\frac{\omega}{z}\right) - \tan^{-1}\left(\frac{\omega}{p}\right)$$

Lets find when  $\angle H(j\omega)$  is max or min!

Recall:  $\frac{d}{dx} \tan^{-1}(x) = \frac{1}{1+x^2}$

# Example 29

1690

$$\frac{d|H(j\omega)|}{d\omega} = \left( \frac{1}{1 + \left(\frac{\omega}{z}\right)^2} \right) \left( \frac{1}{z} \right) - \left( \frac{1}{1 + \left(\frac{\omega}{p}\right)^2} \right) \frac{1}{p} = 0$$

$\downarrow$  multiply top & bottom by  $z^2$                        $\downarrow$  multiply top & bottom by  $p^2$

$$\Rightarrow \frac{z}{z^2 + \omega^2} = \frac{p}{p^2 + \omega^2}$$

$$\Rightarrow z(p^2 + \omega^2) = p(z^2 + \omega^2)$$

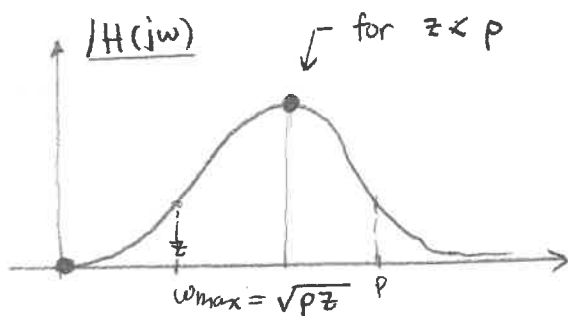
$$\Rightarrow zp^2 + z\omega^2 = pz^2 + p\omega^2$$

$$\Rightarrow (p-z)\omega^2 = zp^2 - pz^2 = zp(p-z)$$

$$\Rightarrow \omega^2 = pz$$

$$\boxed{\omega_{\text{extrema}} = \sqrt{pz}}$$

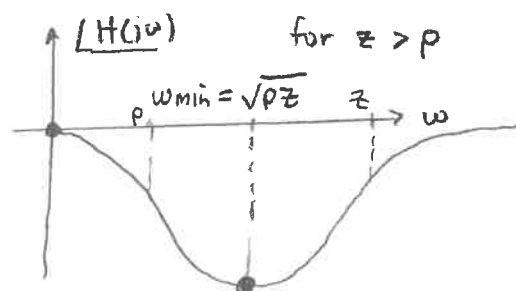
$$\begin{aligned} |H(j\sqrt{pz})| &= \tan^{-1}\left(\frac{\sqrt{pz}}{z}\right) - \tan^{-1}\left(\frac{\sqrt{pz}}{p}\right) \\ &= \tan^{-1}\left(\sqrt{\frac{p}{z}}\right) - \tan^{-1}\left(\sqrt{\frac{z}{p}}\right) \end{aligned}$$



When  $z < p$ ,  $|H(j\omega)| > 0$

∴ we say that H is a Lead filter

(as well as a high pass filter (HPF))  
 $\downarrow$   
because of  
magnitude shape



When  $z > p$ ,  $|H(j\omega)| \leq 0$

∴ we say that H is a Lag Filter.

(as well as a low pass filter (LPF))  
 $\downarrow$   
because of  
magnitude shape


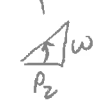
# Example 29

1700

4

$$H(s) = g \left[ \frac{s}{s+p_1} \right] \left[ \frac{p_2}{s+p_2} \right]$$

$$H(j\omega) = g \left[ \frac{j\omega}{j\omega+p_1} \right] \left[ \frac{p_2}{j\omega+p_2} \right]$$

$j\omega = \omega e^{j90^\circ}$   
 $\omega \angle 90^\circ$   
  
 $p_1$   
  
 $p_2$

$$g, p_1, p_2 > 0$$

$$(p_1 \ll p_2)$$

↑  
suppose  
so  $p_1 \ll 0, p_2$   
to facilitate plotting  
of magnitude

$$|H(j\omega)| = \frac{|top|}{|bottom|} = g \left[ \frac{\omega}{\sqrt{\omega^2 + p_1^2}} \right] \left[ \frac{p_2}{\sqrt{\omega^2 + p_2^2}} \right]$$

Note:  $H(0) = 0$   $H(\infty) = 0$

$$|H(jp_1)| = \left| g \left[ \frac{jp_1}{jp_1+p_1} \right] \left[ \frac{p_2}{jp_1+p_2} \right] \right|$$

$$= \left| g \left[ \frac{j1}{1+j1} \right] \left[ \frac{p_2}{p_2+jp_1} \right] \right|$$

$$p_1 \ll p_2 \rightarrow \approx g \frac{1}{\sqrt{2}} \left[ \frac{p_2}{p_2+0} \right]$$

$$\approx \frac{g}{\sqrt{2}}$$

$$|H(j10p_1)| = \left| g \left[ \frac{j10p_1}{j10p_1+p_1} \right] \left[ \frac{p_2}{j10p_1+p_2} \right] \right|$$

$$\approx g \left| \frac{j10p_1}{j10p_1+0} \right| \left| \frac{p_2}{0+p_2} \right|$$

$$\approx g$$

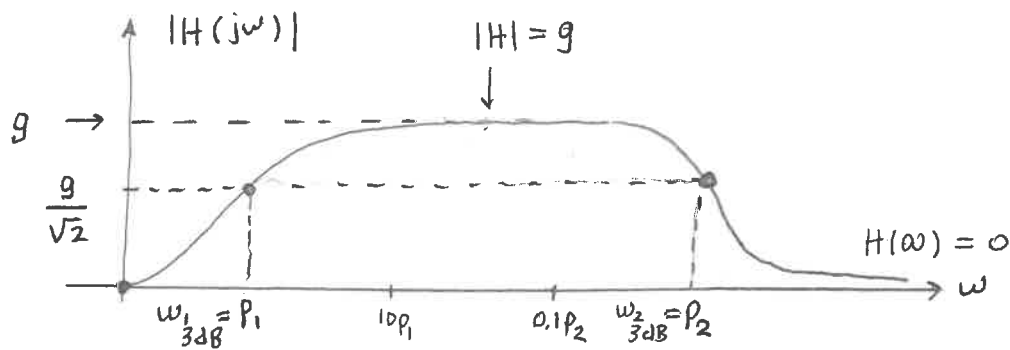
$$|H(jp_2)| = \left| g \left[ \frac{jp_2}{jp_2+p_1} \right] \left[ \frac{p_2}{jp_2+p_2} \right] \right|$$

$$\approx g \left| \frac{jp_2}{jp_2+0} \right| \left| \frac{1}{1+j1} \right|$$

$$\approx \frac{g}{\sqrt{2}}$$

# Example 29

1710



Here,  $H$  is called a band pass filter (BPF).

It is used to pass (or amplify) frequencies between the 3dB frequencies  $p_1 < p_2$  !

$$\angle H(j\omega) = \angle_{\text{top}} - \angle_{\text{bottom}}$$

$$= 90^\circ - \left[ \tan^{-1}\left(\frac{\omega}{p_1}\right) + \tan^{-1}\left(\frac{\omega}{p_2}\right) \right]$$

Note:

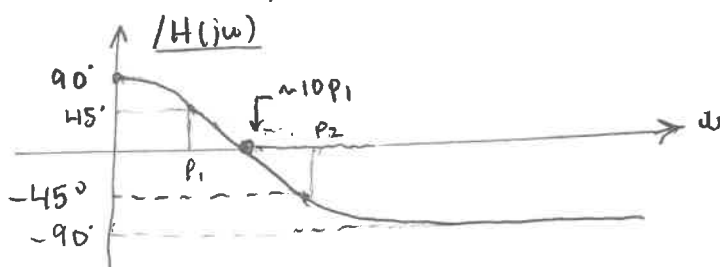
$$\angle H(0) = 90 - 0 - 0 = 90^\circ$$

$$\angle H(jp_1) = 90 - \cancel{\tan^{-1}(1)}^{45^\circ} - \cancel{\tan^{-1}\left(\frac{p_1}{p_2}\right)}^{\sim 0^\circ \text{ since } p_1 < p_2} \cong 45^\circ$$

$$\angle H(j10p_1) = 90 - \cancel{\tan^{-1}(10)}^{\sim 90^\circ} - \cancel{\tan^{-1}\left(\frac{10p_1}{p_2}\right)}^{\sim 0^\circ} \cong 0^\circ$$

$$\angle H(jp_2) = 90 - \cancel{\tan^{-1}\left(\frac{p_2}{p_1}\right)}^{\sim 90^\circ \text{ since } p_2 > p_1} - \cancel{\tan^{-1}(1)}^{45^\circ} \cong 90 - 90 - 45 = -45^\circ$$

$$\angle H(j10p_2) = 90 - \cancel{\tan^{-1}\left(\frac{10p_2}{p_1}\right)}^{\sim 90^\circ} - \cancel{\tan^{-1}(10)}^{\sim 90^\circ} \cong 90 - 90 - 90 = -90^\circ$$



# Example 29

1720

5

$$H(s) = \frac{g s}{p} \left[ \frac{p}{s+p} \right]^2$$

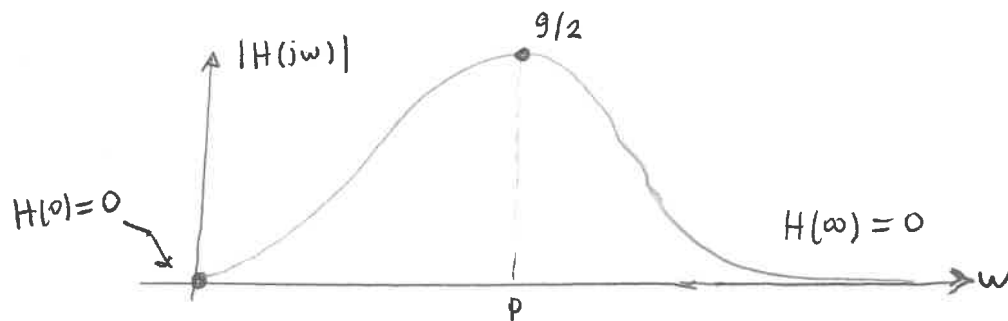
$$g, p > 0$$

$$H(j\omega) = \frac{g}{p} \underbrace{j\omega}_{\substack{\omega \\ \text{hor}}} \left[ \frac{p}{\underbrace{j\omega + p}_{\substack{\omega \\ \text{hor}}}} \right]^2$$

$$|H(j\omega)| = \frac{|top|}{|bottom|} = \frac{\frac{g}{p} \omega p^2}{(\sqrt{\omega^2 + p^2})^2} = \frac{g p \omega}{\omega^2 + p^2}$$

Note:  $H(0) = 0$   $H(\infty) = 0$

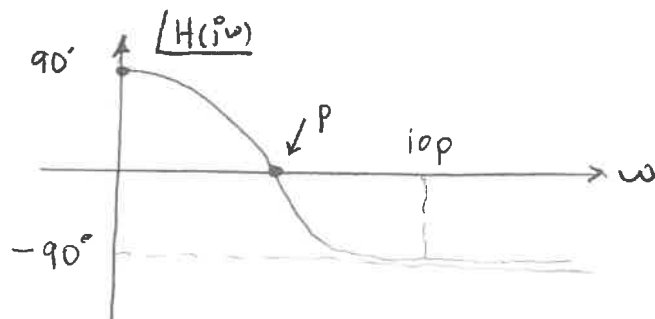
$$|H(jp)| = \frac{g p^2}{p^2 + p^2} = \frac{g}{2}$$



This  $H$  may also be called a band pass filter (BPF).

$$\angle H(j\omega) = \angle top - \angle bottom$$

$$= 90^\circ - 2 \tan^{-1} \left( \frac{\omega}{p} \right)$$



Note:

$$\angle H(0) = 90^\circ$$

$$\begin{aligned} \angle H(jp) &= 90 - 2 \tan^{-1}(1) \\ &= 90 - 2(45^\circ) \\ &= 0^\circ \end{aligned}$$

$$\begin{aligned} \angle H(j10p) &= 90 - 2 \tan^{-1}(10) \\ &\cong 90 - 2(90^\circ) \\ &= -90^\circ \end{aligned}$$

# Example 29

1730

6

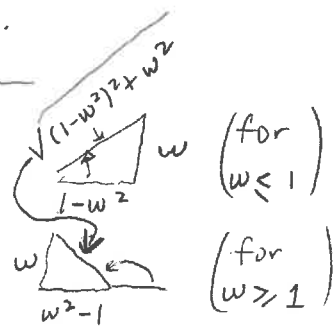
$$H(s) = \frac{10s}{s^2 + s + 1}$$

Note: poles =  $-\frac{1}{2} \pm j\frac{\sqrt{3}}{2}$

$$H(j\omega) = \frac{10j\omega}{- \omega^2 + j\omega + 1}$$

$$= \frac{j10\omega}{1 - \omega^2 + j\omega}$$

$$j10\omega = 10\omega e^{j90^\circ}$$

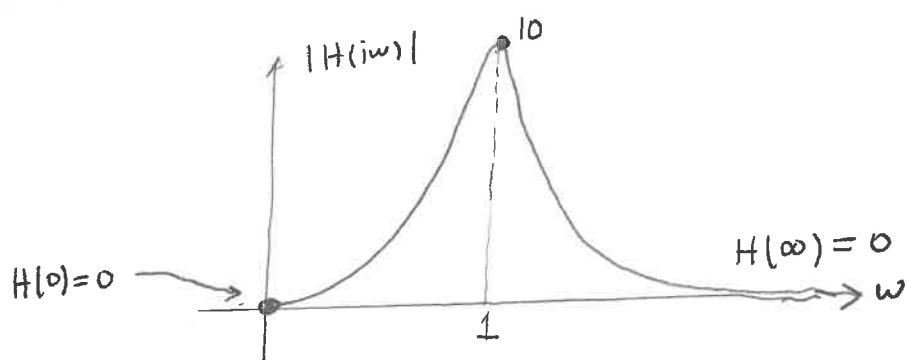


$$|H(j\omega)| = \frac{|top|}{|bottom|} = \frac{10\omega}{\sqrt{(1 - \omega^2)^2 + \omega^2}}$$

Note:  $H(0) = 0$

$$H(j1) = \frac{10j1}{-1 + j1 + 1} = 10$$

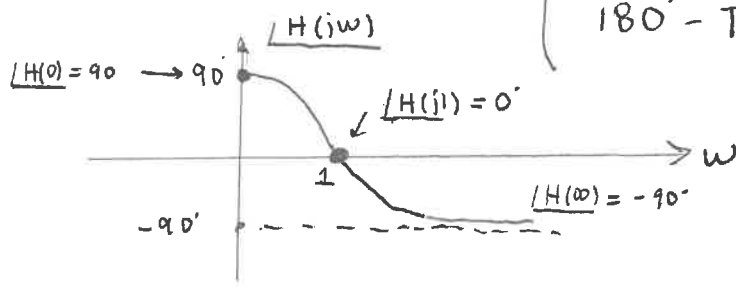
$$H(\infty) = 0 e^{-j90^\circ} \quad (\text{since } H \approx \frac{10}{s} \text{ for large } s)$$



This  $H$  is called a resonant band pass filter (BPF).

$$\angle H(j\omega) = \angle top - \angle bottom$$

$$= 90^\circ - \begin{cases} \tan^{-1}\left(\frac{\omega}{1 - \omega^2}\right) & \text{if } \omega \in [0, 1] \\ 180^\circ - \tan^{-1}\left(\frac{\omega}{\omega^2 - 1}\right) & \text{if } \omega \in [1, \infty) \end{cases}$$



Note:  $\swarrow$  cause  $H \approx 10s$  for small  $s$ !  
 $\angle H(0) = 90$   
 $\angle H(j1) = 90 - 90^\circ = 0^\circ$   
 $\angle H(\infty) = 90 - (180 - 0) = -90^\circ$   
 $\swarrow$  cause  $H \approx \frac{10}{s}$  for large  $s$

# Example 29

1740

[7]

$$H(s) = \frac{20s}{s^2 + 10s + 125}$$

poles =  $-5 \pm j10$

$$H(j\omega) = \frac{20j\omega}{- \omega^2 + 10j\omega + 125} = \frac{j20\omega}{125 - \omega^2 + j10\omega}$$

$$|H(j\omega)| = \frac{|top|}{|bottom|} = \frac{20\omega}{\sqrt{(\omega^2 - 125)^2 + 100\omega^2}}$$

$j20\omega = 20\omega e^{j90^\circ}$

$\text{mag bottom} = \sqrt{(125 - \omega^2)^2 + 100\omega^2}$

for  $\omega \in [0, \sqrt{125}]$

for  $\omega \in [\sqrt{125}, \infty)$

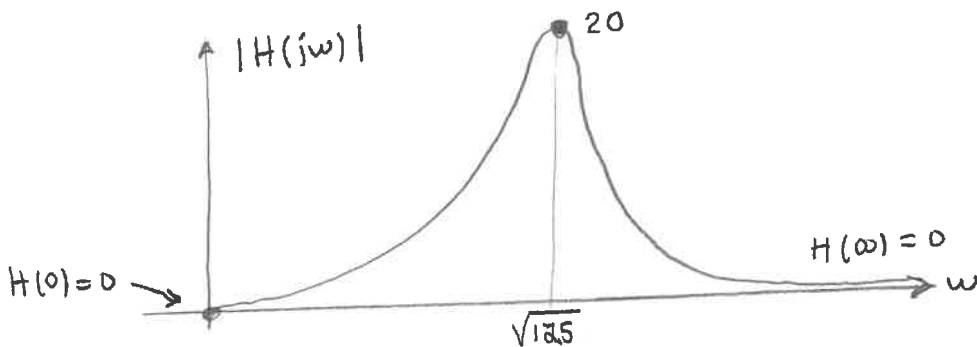
Note:

$$H(0) = 0$$

$$H(s) \approx \frac{20s}{125} \text{ for small } s$$

$$H(j\sqrt{125}) = \frac{200j\sqrt{125}}{-125 + 10j\sqrt{125} + 125} = \frac{200}{10} = 20$$

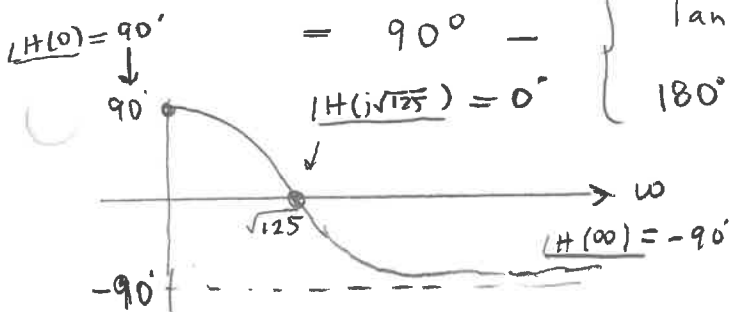
$$H(\infty) = 0 e^{-j90^\circ} \text{ (since } H \approx \frac{20}{s} \text{ for large } s)$$



This  $H$  is called a resonant bandpass filter (BPF).

$$\angle H(j\omega) = \angle top - \angle bottom$$

$$= 90^\circ - \begin{cases} \tan^{-1}\left(\frac{10\omega}{125 - \omega^2}\right) & \text{if } \omega \in [0, \sqrt{125}] \\ 180^\circ - \tan^{-1}\left(\frac{10\omega}{\omega^2 - 125}\right) & \text{if } \omega \in [\sqrt{125}, \infty) \end{cases}$$



Note:  $\angle H(0) = 90^\circ$  since  $H \approx \frac{20s}{125}$  for small  $s$ !

$\angle H(j\sqrt{125}) = 90 - 90 = 0^\circ$

$\angle H(\infty) = 90 - (180 - 0) = -90^\circ$  since  $H \approx \frac{20}{s}$  for large  $s$



# Example 29

1750

undamped natural frequency

↓ damping factor  
 $g, \omega_n, \xi \geq 0$

8

$$H(s) = g \left[ \frac{\omega_n^2}{s^2 + 2\xi\omega_n s + \omega_n^2} \right]$$

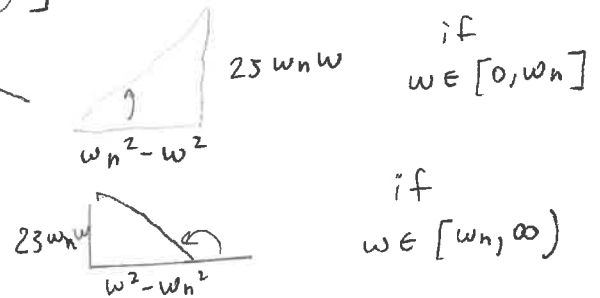
poles =  $-\xi\omega_n \pm \omega_n\sqrt{\xi^2 - 1}$  (for  $\xi \geq 1$ )  
 =  $-\xi\omega_n \pm j\omega_n\sqrt{1 - \xi^2}$  (for  $\xi \in [0, 1]$ )  
 (=  $\pm j\omega_n$  when  $\xi = 0$ )  
 ↑ This is why  $\omega_n$  is called the undamped natural frequency!

$$H(j\omega) = g \left[ \frac{\omega_n^2}{-\omega^2 + 2j\xi\omega_n\omega + \omega_n^2} \right]$$

$$= g \left[ \frac{\omega_n^2}{\omega_n^2 - \omega^2 + j2\xi\omega_n\omega} \right]$$

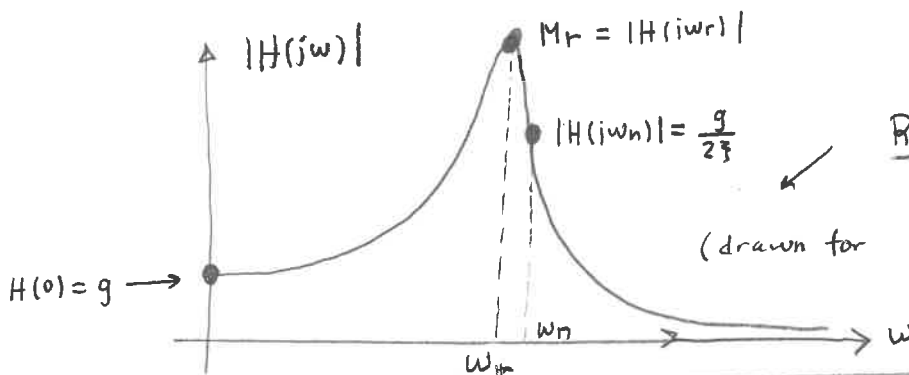
$|H(j\omega)| = \frac{|top|}{|bottom|}$

$$= g \left[ \frac{\omega_n^2}{\sqrt{(\omega_n^2 - \omega^2)^2 + 4\xi^2\omega_n^2\omega^2}} \right]$$



Note:  $H(0) = g$        $H(j\omega_n) = \frac{g}{j2\xi} = \frac{g}{2\xi} e^{-j90^\circ}$

$H(\infty) = 0 e^{-j180^\circ}$   
 since  $H \sim \frac{g\omega_n^2}{s^2}$  for large  $s$



Resonant Band Pass Filter (BPF)

(drawn for  $\xi \in [0, \frac{1}{\sqrt{2}}]$ )

From calculus  
 (or clever algebra)

$$\omega_r = \begin{cases} 0 & \xi \in [\frac{1}{\sqrt{2}}, \infty) \\ \omega_n\sqrt{1 - 2\xi^2} & \xi \in [0, \frac{1}{\sqrt{2}}] \end{cases}$$

$$M_r = |H(j\omega_r)| = \begin{cases} H(0) = g & \xi \in [\frac{1}{\sqrt{2}}, \infty) \\ \frac{g}{2\xi\sqrt{1 - \xi^2}} & \xi \in [0, \frac{1}{\sqrt{2}}] \end{cases}$$

# Example 29

1760

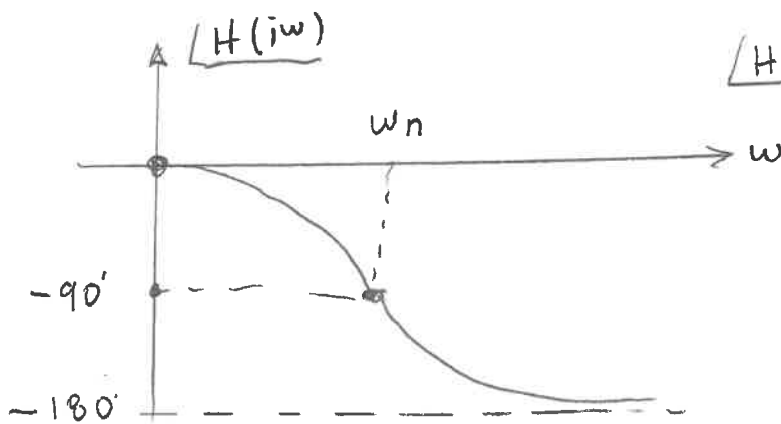
$$\angle H(j\omega) = \angle_{\text{top}} - \angle_{\text{bottom}}$$

$$= 0^\circ - \begin{cases} \tan^{-1}\left(\frac{25\omega_n\omega}{\omega_n^2 - \omega^2}\right) & \text{if } \omega \in [0, \omega_n] \\ 180^\circ - \tan^{-1}\left(\frac{25\omega_n\omega}{\omega^2 - \omega_n^2}\right) & \text{if } \omega \in [\omega_n, \infty) \end{cases}$$

Note =  $\angle H(0) = 0$  since  $H(0) = g > 0$

$$\angle H(j\omega_n) = -90^\circ \text{ since } H(j\omega_n) = \frac{g}{25} e^{-j90^\circ}$$

$$\angle H(\infty) = -[180 - 0] = -180^\circ$$



Lets apply the above

Note = One can just plot points using your calculator!

$$H(s) = 10 \left[ \frac{1}{s^2 + s + 1} \right]$$

$$M_r = \frac{20}{\sqrt{3}}$$

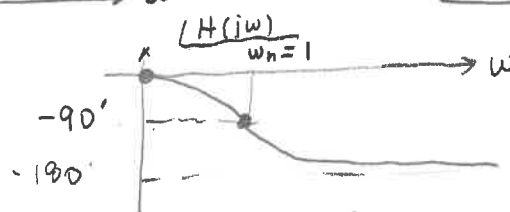
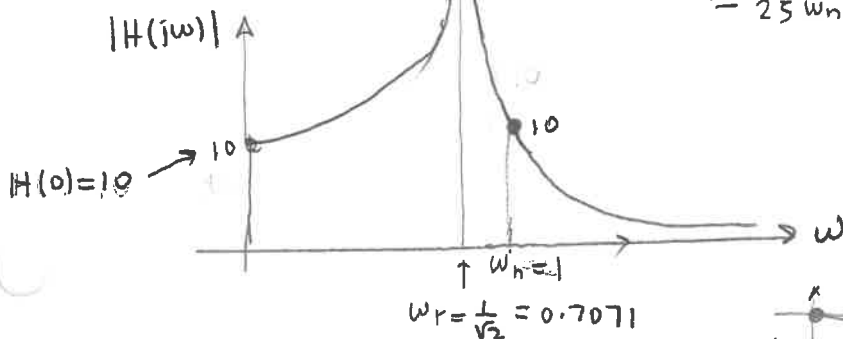
$$\omega_n^2 = 1 \Rightarrow \omega_n = 1$$

$$-25\omega_n = 2\zeta(1) = 1 \Rightarrow \zeta = 0.5$$

- Need not use the formulae.

$$\Rightarrow \omega_r = \omega_n \sqrt{1 - 2\zeta^2} = (1) \sqrt{1 - 2\left(\frac{1}{4}\right)} = \frac{1}{\sqrt{2}}$$

$$M_r = \frac{g}{23\sqrt{1-\zeta^2}} = \frac{10}{2\left(\frac{1}{\sqrt{2}}\right)\sqrt{1-\frac{1}{4}}} = \frac{20}{\sqrt{3}}$$



**Problem 29**

(Transfer Function Frequency Response)

1770

For each of the following transfer functions compute & plot the magnitude response  $|H(j\omega)|$  & phase response  $\angle H(j\omega)$ .

$$[1] \quad H(s) = \frac{10}{s+2}$$

$$[2] \quad H(s) = \frac{60s}{s+3}$$

$$[3] \quad (a) H(s) = 4 \left[ \frac{s+1}{s+100} \right] \quad (b) H(s) = 4 \left[ \frac{s+100}{s+1} \right]$$

$$[4] \quad H(s) = 75 \left[ \frac{s}{s+10} \right] \left[ \frac{10^3}{s+10^3} \right]$$

$$[5] \quad H(s) = 30s \left[ \frac{10}{s+10} \right]^2$$

$$[6] \quad H(s) = \frac{30s}{s^2 + 2s + 101} \quad \text{poles} = ?$$

$$[7] \quad H(s) = \frac{36s}{s^2 + 4s + 2504} \quad \text{poles} = ?$$

$$[8] \quad H(s) = 25 \left[ \frac{1}{s^2 + 0.02s + 1} \right] \quad \text{poles} = ?$$

$$[9] \quad H(s) = 42 \left[ \frac{10^6}{s^2 + 2s + 10^6} \right] \quad \text{poles} = ?$$

Example 30

Laplace Transform Pairs

(More than you will need in circuits !!!)

$$f(t) \leftrightarrow \mathcal{L}\{f(t)\} = F(s) \triangleq \int_0^{\infty} f(\tau) e^{-s\tau} d\tau$$

1780

↑ unilateral Laplace Transform

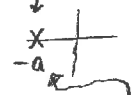
Marginally stable

$$M \delta(t) \leftrightarrow \frac{M}{s} \quad *$$

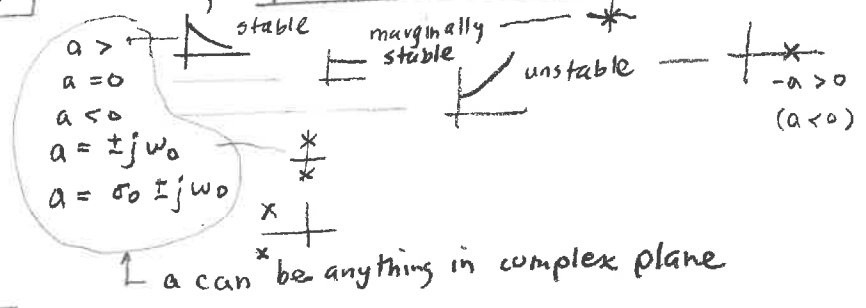
$$Me^{-at} \leftrightarrow \frac{M}{s+a}$$

Holds for any  $a$  !!!

drawn for  $a > 0$



$$e^{-at} f(t) \leftrightarrow F(s+a)$$



unstable

$$t \leftrightarrow \frac{1}{s^2} \quad *$$

$$t f(t) \leftrightarrow -\frac{dF(s)}{ds}$$

unstable

$$\frac{t^n}{n!} \leftrightarrow \frac{1}{s^{n+1}}$$

stable for  $a > 0$

$$M t e^{-at} \leftrightarrow \frac{M}{(s+a)^2}$$

$$M \frac{t^n}{n!} e^{-at} \leftrightarrow \frac{M}{(s+a)^{n+1}}$$

Marginally stable

$$e^{j\omega_0 t} \leftrightarrow \frac{1}{s - j\omega_0} \quad *$$

$$e^{-j\omega_0 t} \leftrightarrow \frac{1}{s + j\omega_0} \quad *$$

$$\cos \omega_0 t \leftrightarrow \frac{s}{s^2 + \omega_0^2} \quad *$$

$$\frac{e^{j\omega_0 t} + e^{-j\omega_0 t}}{2} \leftrightarrow \frac{1}{2} \left[ \frac{1}{s - j\omega_0} + \frac{1}{s + j\omega_0} \right] = \frac{1}{2} \left[ \frac{s + j\omega_0 + s - j\omega_0}{s^2 + \omega_0^2} \right] = \frac{s}{s^2 + \omega_0^2}$$

Recall:

$$\frac{e^{j\omega_0 t} + e^{-j\omega_0 t}}{2} = \text{Re}[e^{j\omega_0 t}] = \cos \omega_0 t$$

# Example 30

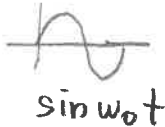
## Laplace Transform Pairs

1790

Recall=

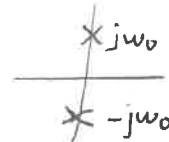
$$\frac{e^{j\omega_0 t} - e^{-j\omega_0 t}}{j2} = \text{Im}[e^{j\omega_0 t}] = \sin \omega_0 t$$

Marginally stable



$\sin \omega_0 t$

$$\frac{\omega_0}{s^2 + \omega_0^2}$$

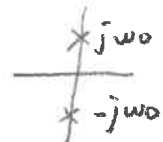


$$\frac{e^{j\omega_0 t} - e^{-j\omega_0 t}}{j2}$$

$$\longleftrightarrow \frac{1}{j2} \left[ \frac{1}{s - j\omega_0} - \frac{1}{s + j\omega_0} \right] = \frac{1}{j2} \left[ \frac{s + j\omega_0 - s + j\omega_0}{s^2 + \omega_0^2} \right] = \frac{\omega_0}{s^2 + \omega_0^2}$$

Recall=  $\cos(x \pm y) = \cos x \cos y \mp \sin x \sin y$

$$|A| \cos(\omega_0 t + \angle A) \longleftrightarrow |A| \cos \angle A \left[ \frac{s - \omega_0 \tan \angle A}{s^2 + \omega_0^2} \right]$$

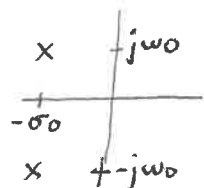


$$|A| \cos \omega_0 t \cos \angle A - |A| \sin \omega_0 t \sin \angle A \longleftrightarrow |A| \left[ \frac{s}{s^2 + \omega_0^2} \cos \angle A - \frac{\omega_0 \sin \angle A}{s^2 + \omega_0^2} \right]$$

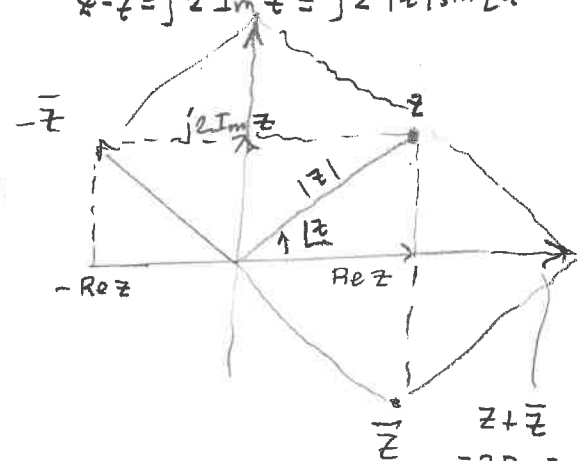
$$|A| e^{-\sigma_0 t} \cos(\omega_0 t + \angle A) \longleftrightarrow |A| \cos \angle A \left[ \frac{s + \sigma_0 - \omega_0 \tan \angle A}{(s + \sigma_0)^2 + \omega_0^2} \right]$$

$$2|A| e^{-\sigma_0 t} \cos(\omega_0 t + \angle A) \longleftrightarrow \frac{A}{s + \sigma_0 - j\omega_0} + \frac{\bar{A}}{s + \sigma_0 + j\omega_0}$$

Very useful  
- comes up when doing partial fraction expansions!



$$z - \bar{z} = j2 \text{Im } z = j2 |z| \sin \angle z$$



$$z + \bar{z} = 2 \text{Re } z = 2|z| \cos \angle z$$

Recall =

$$z + \bar{z} = 2 \text{Re } z = 2|z| \cos \angle z$$

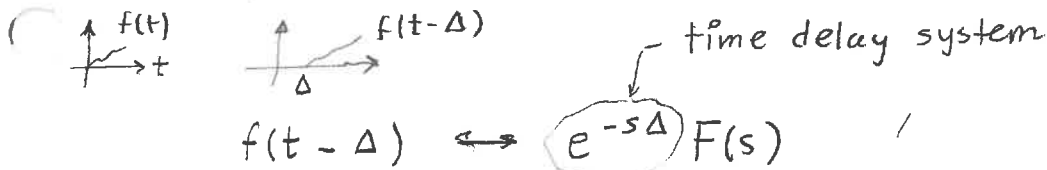
$$z - \bar{z} = j2 \text{Im } z = j2|z| \sin \angle z$$

Euler's formulae

$$|z| e^{j\angle z} = |z| [\cos \angle z + j \sin \angle z]$$

# Laplace Transform Pairs

1800



$$y(t) = (h * u)(t) = \int_0^t h(\tau) u(t-\tau) d\tau \leftrightarrow Y(s) = H(s) U(s)$$

convolution of  $h$  &  $u$

Here  $u \leftrightarrow U$   
 $h \leftrightarrow H$

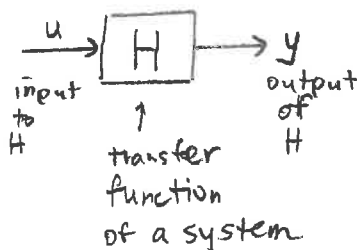
we use this to find the output  $y$  of a system  $H$  with input  $u$

( $\neq$  zero initial conditions!)

- this will involve expanding  $Y$  as a partial fraction expansion & then taking inverse transform term by term

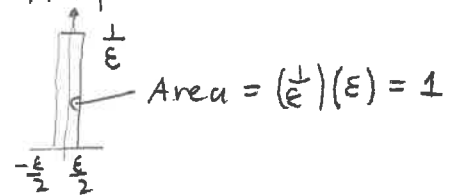
We will not use this in our circuit/system analysis

Useful Interpretation:



$\delta(t) \leftrightarrow 1$   
↑  
Dirac Delta function ...  
unit (impulse function)

mathematical model for a "tall thin pulse" with unit area =



Properties of  $\delta$  =

$$\int_{0^-}^{0^+} \delta(\tau) d\tau = 1 \quad (\text{unit area})$$

$$\int_{a^-}^{a^+} f(\tau) \delta(\tau - a) d\tau = f(a)$$

↑  
sifting property of  $\delta$

we use this to find output  $y$  of a system when we have non-zero initial conditions

$$\dot{y} \leftrightarrow s Y(s) - y_0$$

$$\ddot{y} \leftrightarrow s^2 Y(s) - s y_0 - \dot{y}_0$$

$$y^{(3)} \leftrightarrow s^3 Y(s) - s^2 y_0 - s \dot{y}_0 - \ddot{y}_0$$

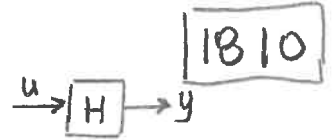
$$y_0 \triangleq y(0)$$

$$\dot{y}_0 \triangleq \dot{y}(0)$$

$$\ddot{y}_0 \triangleq \ddot{y}(0)$$

### Example 30

Suppose we have a transfer function =



$$H(s) = \frac{Y(s)}{U(s)} \Bigg|_{\substack{\text{Zero} \\ \text{Poles}}} = \frac{b_m s^m + b_{m-1} s^{m-1} + \dots + b_1 s + b_0}{a_n s^n + a_{n-1} s^{n-1} + \dots + a_1 s + a_0}$$

then  
 $\Rightarrow$

the associated differential equation relating  $y$  &  $u$  is given by =

$$\begin{aligned} a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_2 y'' + a_1 \dot{y} + a_0 y \\ = b_m u^{(m)} + b_{m-1} u^{(m-1)} + \dots + b_2 \ddot{u} + b_1 \dot{u} + b_0 u \end{aligned}$$

# Example 30

## Initial Value Theorem

1820

Suppose

$$y(t) = y_0 + \dot{y}_0 t + \frac{\ddot{y}_0}{2!} t^2 + \dots$$

$$\rightarrow Y = \frac{y_0}{s} + \frac{\dot{y}_0}{s^2} + \frac{\ddot{y}_0}{s^3} + \frac{\dddot{y}_0}{s^4} + \dots$$

$$sY = y_0 + \frac{\dot{y}_0}{s} + \frac{\ddot{y}_0}{s^2} + \frac{\dddot{y}_0}{s^3} + \dots$$

$$y_0 = \lim_{s \rightarrow \infty} sY(s)$$

$$s[sY - y_0] = \dot{y}_0 + \frac{\ddot{y}_0}{s} + \dots$$

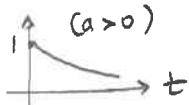
$$\dot{y}_0 = \lim_{s \rightarrow \infty} s^2 Y(s) - s y_0$$

$$s[s[sY - y_0] - \dot{y}_0] = \ddot{y}_0 + \frac{\dddot{y}_0}{s} + \dots$$

$$\ddot{y}_0 = \lim_{s \rightarrow \infty} s^3 Y - s^2 y_0 - s \dot{y}_0$$

$$y_0^{(n)} = \lim_{s \rightarrow \infty} s^n Y - s^{n-1} y_0 - \dots - s^2 y_0^{(n-3)} - s y_0^{(n-2)} - y_0^{(n-1)}$$

Application:

Suppose  $y(t) = e^{-at}$    $\leftrightarrow Y(s) = \frac{1}{s+a}$

We see  $y(0^+) = 1$

Lets use the initial value theorem to get this:

$$y(0^+) = \lim_{s \rightarrow \infty} sY(s) = \lim_{s \rightarrow \infty} s\left(\frac{1}{s+a}\right) = 1 \text{ as expected!}$$





### Example 30

#### Final Value Theorem

1830

Suppose  $y \leftrightarrow Y$

$y_{\infty} = y(\infty) = \text{final value of } y$

Claim:

$$y_{\infty} = \lim_{s \rightarrow 0} s Y(s)$$

Pf:

$$Y(s) = \int_0^{\infty} y(\tau) e^{-s\tau} d\tau \quad \text{suppose } y \approx y_{\infty} \text{ for } t \geq T$$

$$= \int_0^T y(\tau) e^{-s\tau} d\tau + \int_T^{\infty} y_{\infty} e^{-s\tau} d\tau$$

$$= \int_0^T y(\tau) e^{-s\tau} d\tau + y_{\infty} \left. \frac{e^{-s\tau}}{s} \right|_T^{\infty}$$

$$\uparrow \frac{e^{-sT}}{s} - \frac{e^{-s\infty}}{s} \quad 0 \text{ (for } s > 0)$$


$$s Y(s) = s \int_0^T y(\tau) e^{-s\tau} d\tau + y_{\infty} [e^{-sT} - \cancel{e^{-s\infty}}]$$

Now let  $s \rightarrow 0$

$$\lim_{s \rightarrow 0} s Y(s) = 0 + y_{\infty} [1 - 0]$$

$$\Rightarrow y_{\infty} = \lim_{s \rightarrow 0} s Y(s)$$

Application:

Suppose  $y(t) = 1 - e^{-t}$    $\Leftrightarrow Y = \frac{1}{s} - \frac{1}{s+1} = \frac{s+1-s}{s(s+1)} = \frac{1}{s(s+1)}$

We see that  $y_{\infty} = 1$

Let's use the final value theorem to get this:

$$y_{\infty} = \lim_{s \rightarrow 0} s Y(s) = s \frac{1}{s(s+1)} \Big|_{s=0} = \frac{1}{s+1} \Big|_{s=0} = 1 \text{ as expected!}$$



# Example 30

1840

Find  $y(t)$  for the follow  $Y(s)$  by forming a partial fraction expansion & taking Inverse Laplace Transforms term by term

numerator is set to 1 only for simplicity

$$Y(s) = \frac{1}{s(s+1)(s-4)(s^2-s+1)(s^2+2s+2)(s^2+100)}$$

$\text{poles} = -\frac{1}{2} \pm j\frac{\sqrt{3}}{2}$ 
 $\text{poles} = -1 \pm j1$ 
 $\text{poles} = \pm j10$

Here is the partial fraction expansion:

$$Y = \frac{A}{s} + \frac{B}{s+1} + \frac{C}{s-4} + \left[ \frac{D}{s-\frac{1}{2}-j\frac{\sqrt{3}}{2}} + \text{conjugate} \right] + \left[ \frac{E}{s+1-j1} + \text{conjugate} \right] + \left[ \frac{F}{s-j10} + \text{conjugate} \right]$$

$\text{conjugate} = \frac{\bar{D}}{s-\frac{1}{2}+j\frac{\sqrt{3}}{2}}$ 
 $\text{conjugate} = \frac{\bar{E}}{s+1+j1}$ 
 $\text{conjugate} = \frac{\bar{F}}{s+j10}$

using our provided transform pairs we can now get the form of  $y(t) =$

$$y(t) = A + Be^{-t} + Ce^{4t} + 2|D|e^{\frac{1}{2}t} \cos\left(\frac{\sqrt{3}}{2}t + \angle D\right) + 2|E|e^{-t} \cos(t + \angle E) + 2|F| \cos(10t + \angle F)$$

Note: These are growing (unstable) terms!  
 This = yss since it dominates after a long time

We still need to compute the coefficients = A, B, C, D, E, F

Lets now show that they are all computed using the following formula:

$$\text{Coeff} = \lim_{s \rightarrow \text{pole associated with coeff}} (s - \text{pole}) Y(s)$$

we have

$$\Rightarrow Y = \dots + \left[ \frac{\text{coeff}}{s - \text{pole}} + * \right] + \dots$$

To find coeff, multiply both sides by (s-pole)

$$(s - \text{pole}) Y = \text{coeff} + \left[ \text{all other terms} \right] (s - \text{pole})$$

Now take  $\lim_{s \rightarrow \text{pole}}$

This yields

$$\lim_{s \rightarrow \text{pole}} (s - \text{pole}) Y(s) = \text{coeff} + \left[ \text{all other terms} \right] (s - \text{pole}) \Big|_{s = \text{pole}}$$

or

$$\text{coeff} = \lim_{s \rightarrow \text{pole}} (s - \text{pole}) Y(s)$$

as stated above!



From this, it follows therefore that

$$\begin{aligned} \boxed{A = \lim_{s \rightarrow 0} s Y(s)} &= \frac{1}{(s+1)(s-4)(s^2-s+1)(s^2+2s+2)(s^2+100)} \Big|_{s=0} \\ &= \frac{1}{(1)(-4)(1)(2)(100)} \\ \boxed{B = \lim_{s \rightarrow -1} (s+1) Y(s)} &= \frac{1}{s(s-4)(s^2-s+1)(s^2+2s+2)(s^2+100)} \Big|_{s=-1} \\ &= \frac{1}{(-1)(-5)(1+1+1)(1-2+2)(1+100)} \end{aligned}$$

$$C = \lim_{s \rightarrow 4} (s-4) Y(s) = \frac{1}{s(s+1)(s^2-s+1)(s^2+2s+2)(s^2+100)} \Big|_{s=4}$$

$$= \frac{1}{(4)(5)(16-4+1)(16+8+2)(16+100)}$$

$$D = \lim_{s \rightarrow \frac{1}{2} + j\frac{\sqrt{3}}{2}} (s - \frac{1}{2} - j\frac{\sqrt{3}}{2}) Y(s) = \frac{1}{s(s+1)(s-4)(s - \frac{1}{2} + j\frac{\sqrt{3}}{2})(s^2+2s+2)(s^2+100)}$$

$$= \frac{1}{(\frac{1}{2} + j\frac{\sqrt{3}}{2})(\frac{3}{2} + j\frac{\sqrt{3}}{2})(\frac{1}{2} + j\frac{\sqrt{3}}{2} - 4)(j\sqrt{3})(1e^{j120} + 1 + j\sqrt{3} + 2)(1e^{j120} + 100)}$$

$s = \frac{1}{2} + j\frac{\sqrt{3}}{2} = 1e^{j60}$

etc... you can do the rest

$$E = \lim_{s \rightarrow -1+j1} (s+1-j1) Y(s) = \frac{1}{s(s+1)(s-4)(s^2-s+1)(s+1+j1)(s^2+100)} \Big|_{s=-1+j1}$$

$$= \frac{1}{(-1+j1)(j1)(-5+j1)(2e^{j270} + 1 - j1 + 1)(j2)(2e^{j270} + 100)}$$

$s = -1+j1 = \sqrt{2}e^{j135}$

etc... you can do the rest

$$F = \lim_{s \rightarrow j10} (s-j10) Y(s) = \frac{1}{s(s+1)(s-4)(s^2-s+1)(s^2+2s+2)(s+j10)} \Big|_{s=j10}$$

$$= \frac{1}{(j10)(j10+1)(j10-4)(-100-j10+1)(-100+j20+2)(j20)}$$

etc... you can do the rest

Important Note:

The most important coefficients to compute are always those with critical steady state constants, sinusoids, & growing signals!

# Example 30

1870

## Inverse Transform

For each  $Y$ , find  $y(t)$ ,  $y_{ss}$ , &  $t_s$ .

1  $Y(s) = \left[ \frac{1}{s+1} \right] \frac{10}{s}$

solution:

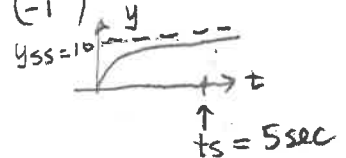
$$Y = \frac{A}{s} + \frac{B}{s+1}$$

$$\Rightarrow y = \overset{y_{ss}}{A} + \overset{\text{stable (decaying exponential)}}{B e^{-t}}$$

$$A = \lim_{s \rightarrow 0} s Y = s \left[ \frac{1}{s+1} \right] \frac{10}{s} \Big|_{s=0} = 10 \left[ \frac{1}{s+1} \right] \Big|_{s=0} = 10(1)$$

$$B = \lim_{s \rightarrow -1} (s+1) Y = (s+1) \left[ \frac{1}{s+1} \right] \frac{10}{s} \Big|_{s=-1} = \left( \frac{10}{-1} \right) = -A$$

$$\Rightarrow y = 10(1) [1 - e^{-t}]$$



2  $Y(s) = \left[ \frac{1}{s+1} \right] \left[ \frac{1}{s^2+1} \right]$

solution:

$$Y = \frac{A}{s+1} + \frac{B}{s-j1} + \frac{B^*}{s+j1}$$

poles =  $\pm j1$

$$\Rightarrow y = A e^{-t} + 2|B| \cos(t + \angle B)$$

$$A = \lim_{s \rightarrow -1} (s+1) Y = \frac{1}{s^2+1} \Big|_{s=-1} = \frac{1}{2}$$

$$B = \lim_{s \rightarrow j1} (s-j1) Y = \left( \frac{1}{s+1} \right) \left( \frac{1}{s+j1} \right) \Big|_{s=j1} = \left( \frac{1}{j1+1} \right) \left( \frac{1}{j2} \right) = \left( \frac{1}{\sqrt{2} e^{j45^\circ}} \right) \left( \frac{1}{2 e^{j90^\circ}} \right) = \frac{1}{2\sqrt{2}} e^{-j135^\circ}$$

$$\Rightarrow y = \frac{1}{2} e^{-t} + \frac{1}{\sqrt{2}} \cos(t - 135^\circ)$$

Note:  
 $\cos(x-90) = \sin x$

$$= \frac{1}{2} e^{-t} + \frac{1}{\sqrt{2}} \sin(t - 45^\circ)$$

$y_{ss}$

# Example 30

1880

## Inverse Transforms

$$3 \quad Y(s) = \left[ \frac{1}{s-3} \right] \left[ \frac{9}{s} \right]$$

solution:

$$Y = \frac{A}{s} + \frac{B}{s-3} \Rightarrow$$

$$y = A + B e^{3t} \quad \text{unstable (growing exponential!)} \quad y_{ss}$$

$$A = \lim_{s \rightarrow 0} sY = \frac{9}{s-3} \Big|_{s=0} = -3$$

$$B = \lim_{s \rightarrow 3} (s-3)Y = \frac{9}{s} \Big|_{s=3} = 3$$

$$y = 3[-1 + e^{3t}]$$

$$y_{ss} = B e^{3t} = 3 e^{3t}$$

↑ unstable (growing exponential)

How do we find a settling time here?

Answer =

$$\text{When is } \left| \frac{y - y_{ss}}{y_{ss}} \right| \leq 0.1 ?$$

$$\Rightarrow y = -3 + y_{ss}$$

$$\Rightarrow y - y_{ss} = -3 ; y_{ss} = 3e^{3t}$$

$$\Rightarrow \left| \frac{y - y_{ss}}{y_{ss}} \right| = \left| \frac{-3}{3e^{3t}} \right| = e^{-3t} \leq 0.1$$

$$10 \leq e^{3t}$$

$$\ln 10 \leq 3t$$

$$\frac{\ln 10}{3} \leq t$$

$$\Rightarrow t_{s \text{ } 1\%} = \frac{\ln 10}{3}$$

# Example 30

1890

$$[4] \quad Y(s) = \left( \frac{1}{s-1} \right) \left[ \frac{100}{s^2 + 104} \right]$$

↑ poles =  $\pm j100$

solution =

$$y = \frac{A}{s-1} + \frac{B}{s-j100} + *$$

conjugate =  $\frac{\bar{B}}{s+j100}$

unstable (growing exponential)

$$y = \underbrace{A e^t}_{y_{ss}} + 2|B| \cos(100t + \angle B)$$

$$A = \lim_{s \rightarrow 1} (s-1)Y = \frac{100}{s^2 + 104} \Big|_{s=1}$$

$$= \frac{100}{1+104}$$

$$\cong 10^{-2}$$

$$B = \lim_{s \rightarrow j100} (s-j100)Y = \left[ \frac{1}{s-1} \right] \frac{100}{(s+j100)} \Big|_{s=j100}$$

$$= \left( \frac{1}{j100-1} \right) \frac{1}{j2}$$

$$\cong \left( \frac{1}{100 e^{j90^\circ}} \right) \left( \frac{1}{2 e^{j90^\circ}} \right)$$

$$\cong \frac{1}{200} e^{-j180^\circ}$$

$$\Rightarrow y \cong 10^{-2} e^t + \frac{1}{100} \cos(100t - 180^\circ)$$

↑  $\cos(x - 90^\circ) = \sin x$

$$\cong \underbrace{10^{-2} e^t}_{y_{ss} \text{ (unstable growing exponential)}} + 10^{-2} \sin(100t - 90^\circ)$$

How do we find a settling time here?

Answer =

When is  $\left| \frac{y - y_{ss}}{y_{ss}} \right| \leq 0.1$ ?

$$\Rightarrow \left| \frac{y - y_{ss}}{y_{ss}} \right| = \frac{|10^{-2} \sin(100t - 90^\circ)|}{10^{-2} e^t}$$

$$\leq \frac{10^{-2}}{10^{-2}} e^{-t} \leq 0.1$$

$$10 \leq e^t$$

$$\ln 10 \leq t$$

$$t_{1\%} = \ln 10$$

## Example 30

5  $Y(s) = \left[ \frac{1}{s-1} \right] \left[ \frac{s^2+s+1}{s(s^2+1)} \right]$   
 $\uparrow$  poles =  $\pm j1$

Solution:

$$Y = \frac{A}{s-1} + \frac{B}{s} + \frac{C}{s-j1} + \text{conjugate} = \frac{\bar{C}}{s+j1}$$

$$y = \underbrace{A e^t}_{\substack{\text{unstable} \\ \text{(growing exponential)}}} + B + 2|C| \cos(t + \angle C)$$

$$A = \lim_{s \rightarrow 1} (s-1)Y = \left. \frac{s^2+s+1}{s(s^2+1)} \right|_{s=1} = \frac{1+1+1}{(1)(1+1)} = \frac{3}{2}$$

$$B = \lim_{s \rightarrow 0} sY = \left[ \frac{1}{s-1} \right] \left[ \frac{s^2+s+1}{s^2+1} \right] \bigg|_{s=0} = (-1)(1) = -1$$

$$C = \lim_{s \rightarrow j1} (s-j1)Y = \left[ \frac{1}{s-1} \right] \left[ \frac{s^2+s+1}{s(s+j1)} \right] \bigg|_{s=j1}$$

$$= \left[ \frac{1}{j1-1} \right] \left[ \frac{-1+j1+1}{(j1)(j2)} \right]$$

$$= \left[ \frac{1/2}{(-1+j1)} \right] \left[ \frac{1}{j2} \right] = \left( \frac{1/2}{\sqrt{2} e^{j135^\circ}} \right) \left( \frac{1}{e^{j90^\circ}} \right) = \frac{1}{2\sqrt{2}} e^{-j225^\circ}$$

$$\begin{matrix} \sqrt{2} & 135^\circ \\ 1 & 45^\circ \end{matrix}$$

$$135^\circ + 90^\circ$$

$$y = \frac{3}{2} e^t + (-1) + \frac{1}{\sqrt{2}} \cos(t - 225^\circ)$$

$$= \frac{3}{2} e^t + (-1) + \frac{1}{\sqrt{2}} \sin(t - 135^\circ) \quad \leftarrow \sin(x) = \cos(x - 90^\circ)$$

$$t_{1\%} = \ln \left[ \frac{20(1 + \frac{1}{\sqrt{2}})}{3} \right]$$

$\uparrow$  yss (unstable growing exponential)

How do we find a settling time here? Answer: When is  $\left| \frac{y - y_{ss}}{y_{ss}} \right| \leq 0.1$ ?

$$\Rightarrow \left| \frac{y - y_{ss}}{y_{ss}} \right| = \left| \frac{-1 + \frac{1}{\sqrt{2}} \sin(t - 135^\circ)}{\frac{3}{2} e^t} \right| \leq \frac{1 + \frac{1}{\sqrt{2}}}{\frac{3}{2} e^t} = \frac{2(1 + \frac{1}{\sqrt{2}})}{3} e^{-t} \leq 0.1$$

$$\Rightarrow \frac{20(1 + \frac{1}{\sqrt{2}})}{3} \leq e^t$$

$$\Rightarrow \ln \left[ \frac{20(1 + \frac{1}{\sqrt{2}})}{3} \right] \leq t$$



# Example 30

2000

$$6 \quad Y(s) = \left[ \frac{100}{(s+1)(s+2)(s+10)} \right] \left[ \frac{10}{s} \right]$$

solutions:

$$Y = \frac{A}{s} + \frac{B}{s+1} + \frac{C}{s+2} + \frac{D}{s+10}$$

slowest pole at  $s = -1 \Rightarrow ts = 5\tau = \frac{5}{|real\ pole|} = \frac{5}{1-1} = 5 \text{ sec}$

$$y = \overset{\downarrow y_{ss}}{\textcircled{A}} + Be^{-t} + Ce^{-2t} + De^{-10t}$$

$$A = \lim_{s \rightarrow 0} sY = \left[ \frac{100}{(s+1)(s+2)(s+10)} \right] \frac{10}{s} \Big|_{s=0} = \left[ \frac{(100)!}{(1)(2)(10)} \right] 10 = (5)(10)$$

$$B = \lim_{s \rightarrow -1} (s+1)Y = \left[ \frac{100}{(s+2)(s+10)} \right] \frac{10}{s} \Big|_{s=-1} = \left[ \frac{100}{(1)(9)} \right] \frac{10}{-1} = -\frac{1000}{9}$$

$$C = \lim_{s \rightarrow -2} (s+2)Y = \left[ \frac{100}{(s+1)(s+10)} \right] \frac{10}{s} \Big|_{s=-2} = \left[ \frac{100}{(-1)(8)} \right] \frac{10}{-2} = \frac{125}{2}$$

$$D = \lim_{s \rightarrow -10} (s+10)Y = \left[ \frac{100}{(s+1)(s+2)} \right] \frac{10}{s} \Big|_{s=-10} = \left[ \frac{100}{(-9)(-8)} \right] \frac{10}{-10} = -\frac{25}{18}$$

$$y = \overset{\downarrow y_{ss}}{\textcircled{10(5)}} - \frac{1000}{9} e^{-t} + \frac{125}{2} e^{-2t} - \frac{25}{18} e^{-10t}$$

$\uparrow$   
 $ts = 5 \text{ sec}$

# Example 30

2010

$$7 \quad Y(s) = \left[ \frac{250}{(s+7)(s^2+6s+25)} \right] \left[ \frac{4}{s} \right]$$

solution:

↑  
fast pole

↑  
poles =  $-3 \pm j4$

↑  
slow poles

$$t_s = \frac{5}{|\text{Re pole}|} = \frac{5}{|-3|} = \frac{5}{3}$$

$$Y = \frac{A}{s} + \frac{B}{s+7} + \frac{C}{s+3-j4} + \text{conjugate} = \frac{\bar{C}}{s+3+j4}$$

$$y = \underset{\substack{\uparrow \\ y_{ss}}}{A} + B e^{-7t} + 2|C| e^{-3t} \cos(4t + \angle C)$$

$$A = \lim_{s \rightarrow 0} s Y = \left[ \frac{250}{(s+7)(s^2+6s+25)} \right] 4 \Big|_{s=0} = \left[ \frac{250}{(7)(25)} \right] 4 = 4 \left( \frac{10}{7} \right)$$

$$B = \lim_{s \rightarrow -7} (s+7) Y = \left[ \frac{250}{s^2+6s+25} \right] \frac{4}{s} \Big|_{s=-7} = \left[ \frac{250}{49-42+25} \right] \frac{4}{-7} = -\frac{125}{28}$$

$$C = \lim_{s \rightarrow -3+j4} (s+3-j4) Y = \left[ \frac{50}{(s+7)(s+3+j4)} \right] \frac{4}{s} \Big|_{s=-3+j4}$$

$$= \left[ \frac{50}{(4+j4)(j4)} \right] \frac{4}{-3+j4}$$

$\begin{array}{c} 4 \\ \swarrow \searrow \\ 4 \end{array}$ 
 $\begin{array}{c} 8e^{j90^\circ} \\ | \\ j4 \end{array}$ 
 $\begin{array}{c} 4 \\ \swarrow \searrow \\ 3 \end{array}$ 
 $\begin{array}{c} 127^\circ \\ \swarrow \searrow \\ 53^\circ \end{array}$

$$= \left[ \frac{50}{(4\sqrt{2}e^{j45^\circ})(8e^{j90^\circ})} \right] \frac{4}{5e^{j127^\circ}}$$

$$= \frac{2.5}{2\sqrt{2}} e^{-j(45+90+127^\circ)} = \frac{2.5}{2\sqrt{2}} e^{-j262^\circ}$$

$$y = \underset{\substack{\uparrow \\ y_{ss}}}{4 \left( \frac{10}{7} \right)} - \frac{125}{28} e^{-7t} + \frac{2.5}{\sqrt{2}} e^{-3t} \cos(4t - 262^\circ)$$

$$\uparrow \\ t_s = \frac{5}{3}$$

# Example 30

2020

$$Y(s) = \left[ \frac{1}{s^2 + s + 1} \right] \left[ \frac{10s^2 + s + 10}{s(s^2 + 1)} \right]$$

$\uparrow$  poles =  $-\frac{1}{2} \pm j\frac{\sqrt{3}}{2}$ 
 $\uparrow$  poles =  $\pm j1$

Solution:

$$Y = \frac{A}{s} + \left[ \frac{B}{s + \frac{1}{2} - j\frac{\sqrt{3}}{2}} + * \right] + \left[ \frac{C}{s - j1} + * \right] \quad y_{ss}$$

$\uparrow$   $t_s = \frac{5}{|Re pole|} = \frac{5}{1 - \frac{1}{2}} = 10 \text{ sec}$

$$y = A + 2|B|e^{-\frac{1}{2}t} \cos\left(\frac{\sqrt{3}}{2}t + \angle B\right) + 2|C|\cos(t + \angle C)$$

decaying exponential:  $t_s = 10 \text{ sec}$

$$A = \lim_{s \rightarrow 0} sY = \left[ \frac{1}{s^2 + s + 1} \right] \left[ \frac{10s^2 + s + 10}{s^2 + 1} \right] \Big|_{s=0} = (1) \left( \frac{10}{1} \right) = (10)(1)$$

$$B = \lim_{s \rightarrow -\frac{1}{2} + j\frac{\sqrt{3}}{2}} (s + \frac{1}{2} - j\frac{\sqrt{3}}{2}) Y = \left[ \frac{1}{s + \frac{1}{2} + j\frac{\sqrt{3}}{2}} \right] \left[ \frac{10s^2 + s + 10}{s^2 + 1} \right] \Big|_{s = -\frac{1}{2} + j\frac{\sqrt{3}}{2}}$$

$\frac{\sqrt{3}}{2}$   $\angle 120^\circ$   $\frac{1}{2}$   $\angle 60^\circ$

$$= \left[ \frac{1}{j\sqrt{3}} \right] \left[ \frac{0e^{j240} - \frac{1}{2} + j\frac{\sqrt{3}}{2} + 10}{e^{j240} + 1} \right] = 1e^{j120^\circ}$$

$\frac{\sqrt{3}}{2}$   $\angle 60^\circ$   $\frac{1}{2}$   $\angle 120^\circ$

$$C = \lim_{s \rightarrow j1} (s - j1) Y = \left[ \frac{1}{s^2 + s + 1} \right] \left[ \frac{10s^2 + s + 10}{s(s + j1)} \right] \Big|_{s=j1}$$

$$= \left( \frac{1}{-1 + j1 + 1} \right) \left( \frac{-10 + j1 + 10}{(j1)(j2)} \right)$$

$$= -\left( \frac{1}{jk} \right) \left( \frac{1}{(j1)(j2)} \right)$$

$$= \frac{1}{(1)(2) e^{j(90+90)}}$$

$$= \left[ \frac{1}{\sqrt{3} e^{j90^\circ}} \right] \left[ \frac{4.5 + j5.5\sqrt{3}}{\frac{1}{2} - j\frac{\sqrt{3}}{2}} \right]$$

$$= \frac{(4.5)^2 + (5.5\sqrt{3})^2}{(\sqrt{3})(1)} e^{j(\tan^{-1}(\frac{5.5\sqrt{3}}{4.5}) - 90^\circ - (-60^\circ))}$$

$\frac{1}{2}$   $\angle 60^\circ$   $\frac{\sqrt{3}}{2}$

Note: A & C are much more important to compute than B because A & C are associated with  $y_{ss}$  & B is associated with a decaying exponential with  $t_s = 10 \text{ sec}$ .

$$y = (10)(1) + 2\cos(t - 180^\circ) + 2|B|e^{-\frac{1}{2}t} \cos\left(\frac{\sqrt{3}}{2}t + \angle B\right)$$

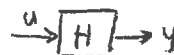
$\uparrow$   $t_s = 10 \text{ sec}$

$$= \sin(t - 90^\circ)$$

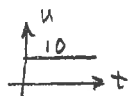
# Problem 30

2030

For each of the following systems  $H$ , find  $y(t)$ , yes,  $t$ s



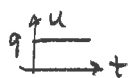
1)  $H(s) = \frac{1}{s+1}$



2)  $H(s) = \frac{1}{s+1}$

$u(t) = \sin t$

3)  $H(s) = \frac{1}{s-3}$



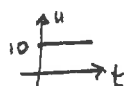
4)  $H(s) = \frac{1}{s-1}$

$u(t) = \sin 100t$

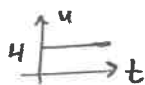
5)  $H(s) = \frac{1}{s-1}$

$u(t) = 1 + \sin t$

6)  $H(s) = \frac{100}{(s+1)(s+2)(s+3)}$



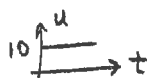
7)  $H(s) = \left[ \frac{250}{(s+1)(s^2+6s+25)} \right]$



8)  $H(s) = \left[ \frac{1}{s^2+s+1} \right]$

$u(t) = 10 + \sin t$

9)  $H(s) = \frac{s}{s+1}$



10)  $H(s) = \frac{s^2+9}{s^2+s+1}$

$u(t) = \cos(3t - 60^\circ)$

Hint:

See  $\S$  we 1-8 in Example 30.

(pages 1870-2020)